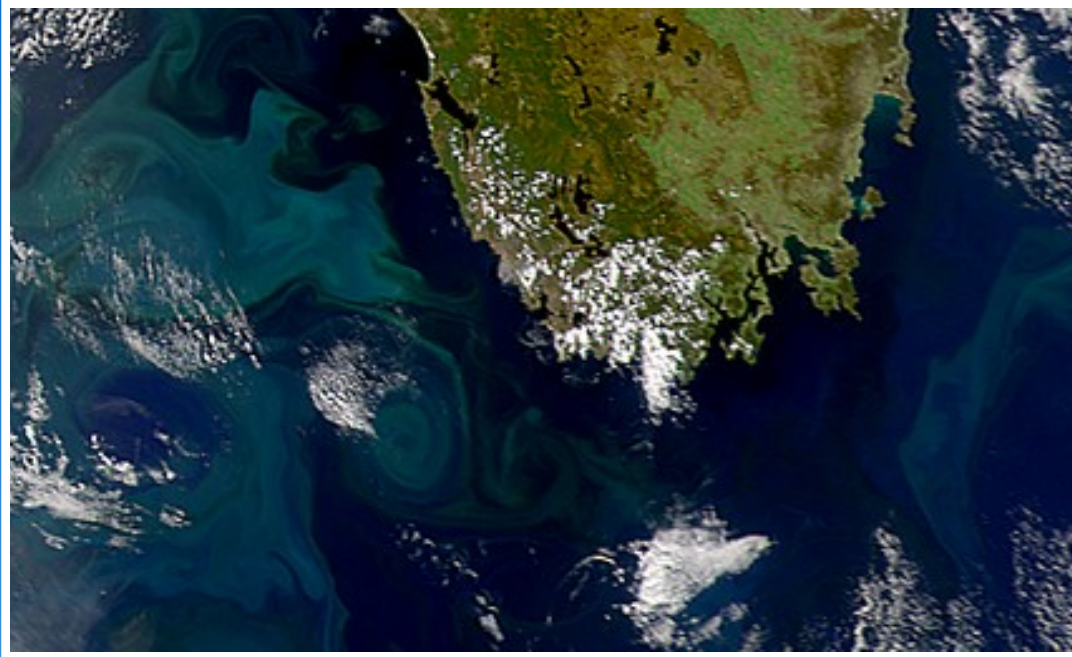




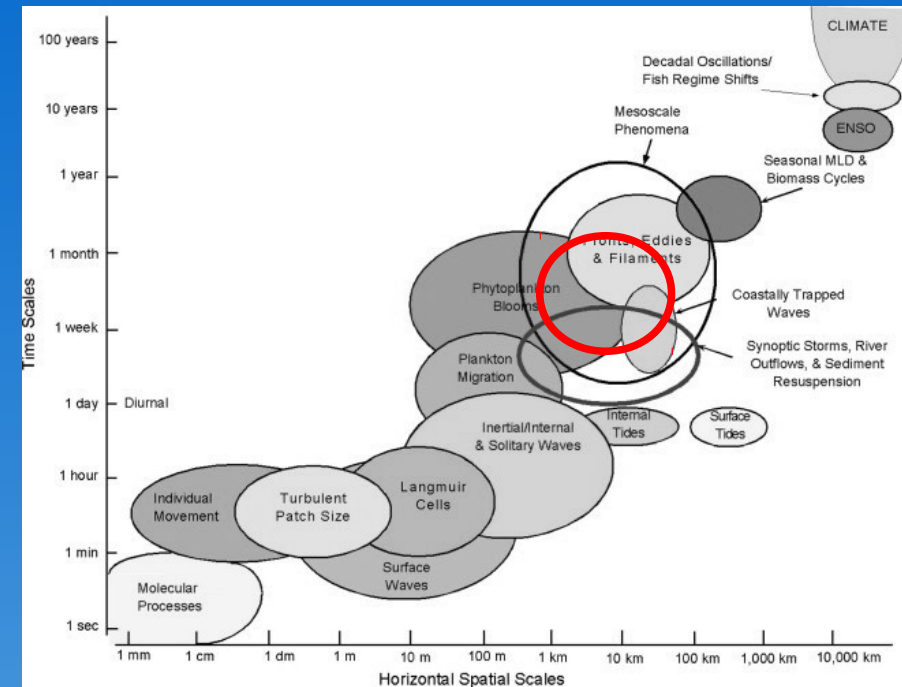
# *In-situ estimate of submesoscale horizontal eddy diffusion coefficients across a front*

F. Nencioli <sup>1</sup>, F. d'Ovidio <sup>2</sup>, A.M. Doglioli <sup>1</sup>, A.A. Petrenko <sup>1</sup>

- (1) Aix-Marseille Université, Mediterranean Institute of Oceanography (MIO), 13288, Marseille, Cedex 9, France ; Université du Sud Toulon-Var; CNRS-INSU/IRD UM 110
- (2) Laboratoire d'Océanographie et du Climat: Experimentation et Approches Numeriques, IPSL, Paris, France



(from <http://oceanservice.noaa.gov/>)



(from Dickey et al., *J. Mar. Syst.*, 2003)

→ **Fronts, jets and eddies: Horizontal scales  $\sim$ (100m - 10km)**  
**Time scales  $\sim$ (days - week)**

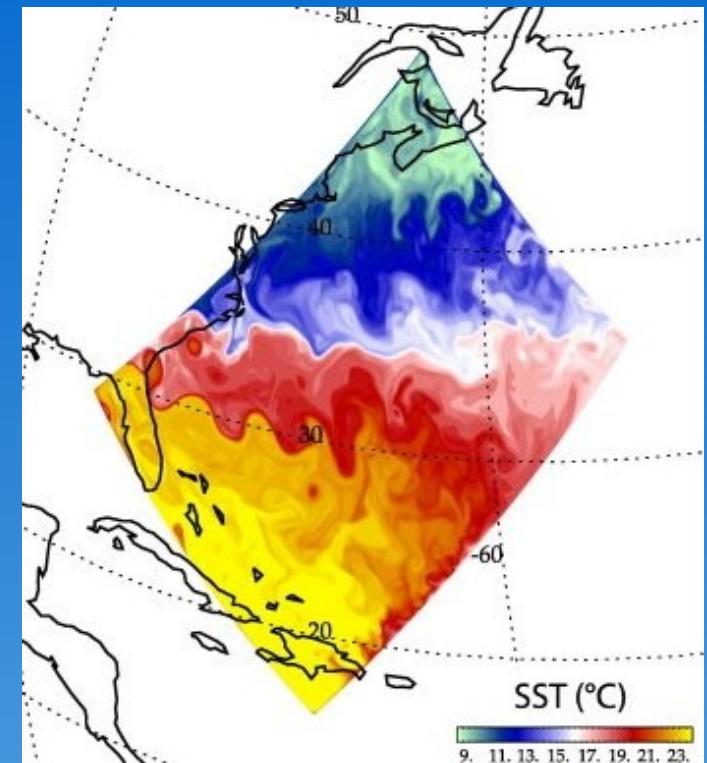
→ **Key role for :** Energy transfer  
 Horizontal and vertical transport  
 Biogeochemical cycles

## → Numerical model studies

Favored by:

Advances in computational power

Development of regional models



(from Levy et al., *Ocean Model.*, 2012)

## → Numerical model studies

Favored by:

Advances in computational power

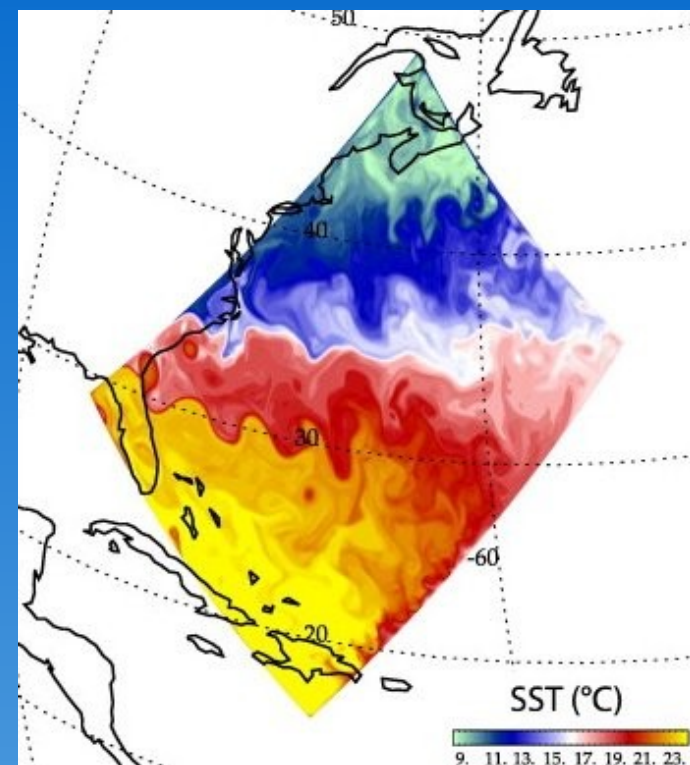
Development of regional models

## → In-situ observations

Challenging due to small spatial  
and temporal scales



Limited estimates of key physical parameters



(from Levy et al., *Ocean Model.*, 2012)

## → Numerical model studies

Favored by:

Advances in computational power

Development of regional models

## → In-situ observations

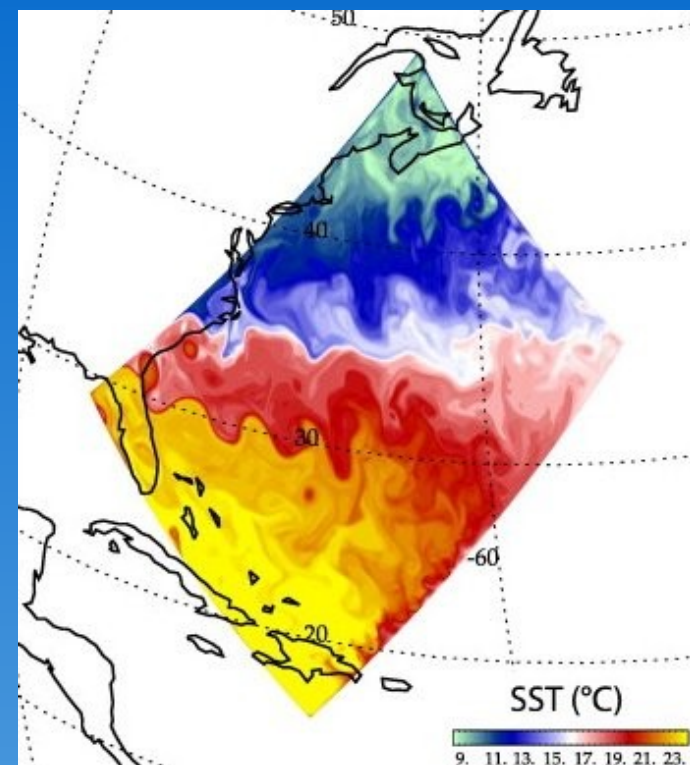
Challenging due to small spatial  
and temporal scales



Limited estimates of key physical parameters

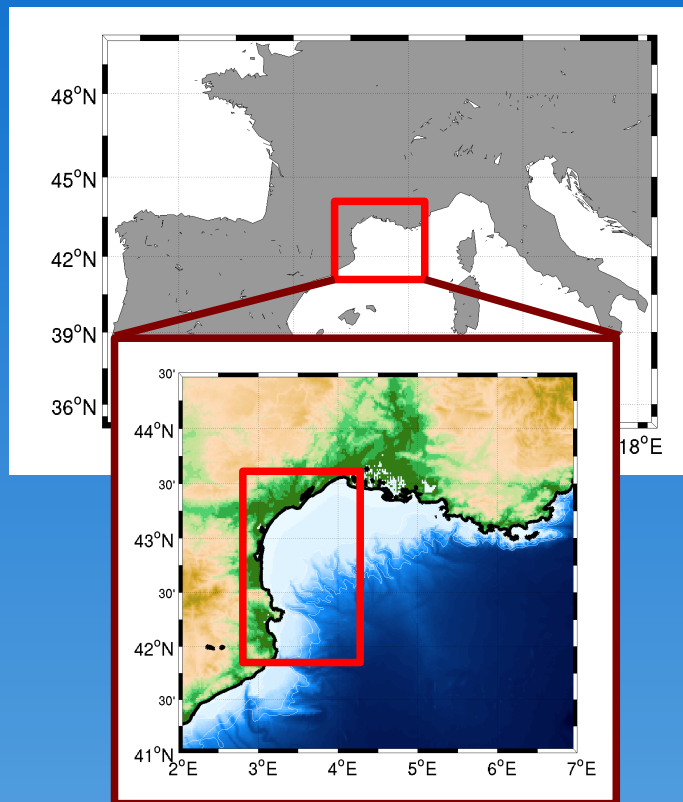
## Focus of this study

New approach to estimate horizontal eddy diffusion coefficients ( $K_h$ ) from in-situ observations



(from Levy et al., Ocean Model., 2012)

→ Latex10 campaign (September 1-24, 2010)

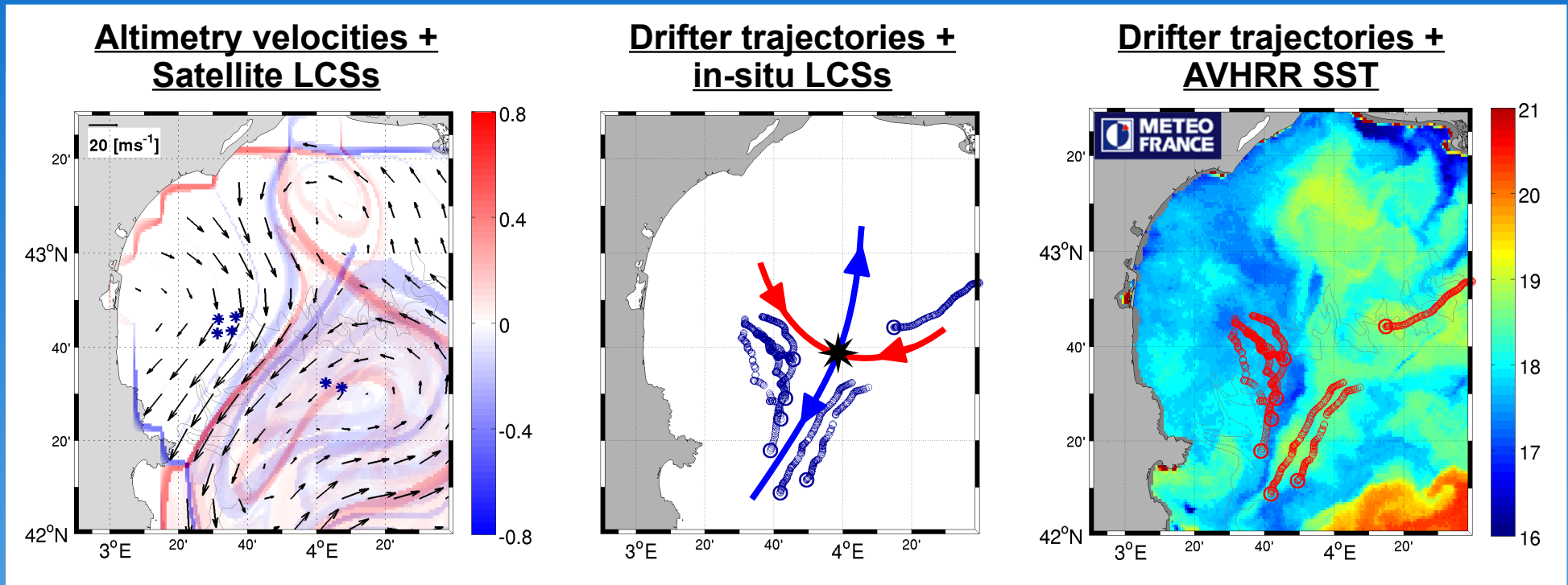


- **Western part of Gulf of Lion (NW Mediterranean)**
- **Main goals : (Sub)mesoscale dynamics**  
**Cross-shelf exchanges**
- **Adaptive sampling strategy based on :**
  - Satellite data
  - Ship-based current measurements
  - Iterative Lagrangian drifter releases



Example:

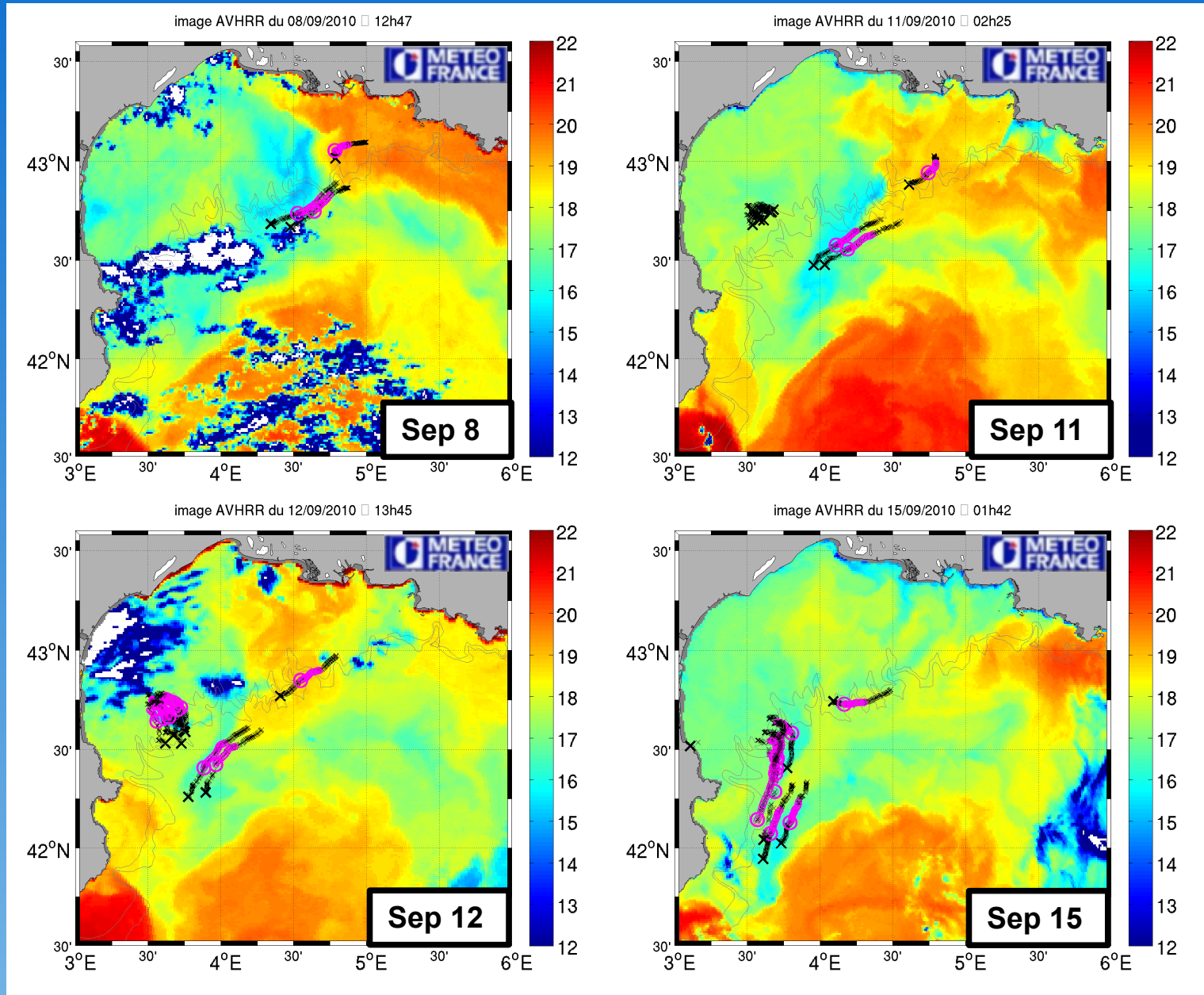
→ Drifter array deployment “Lyap01” (Sep. 15, 2010)



(from Nencioli et al., GRL, 2011)

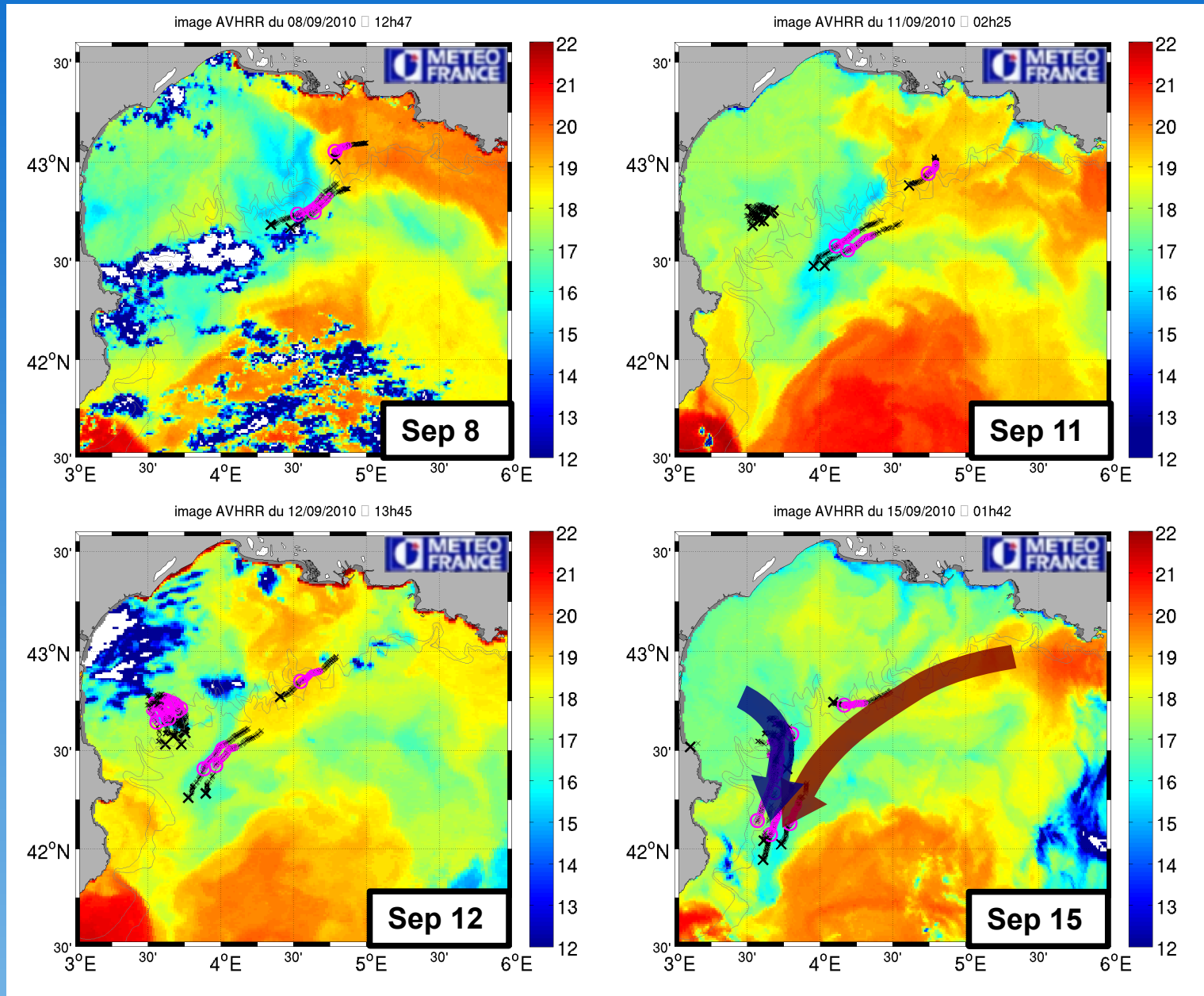
- Identified in-situ Lagrangian Coherent Structures (LCSs)
- Evidenced inaccuracy of altimetry in coastal region
- LCS associated with a frontal structure

## → AVHRR SST + 3-day drifter trajectories (Sep. 8 to 15, 2010)



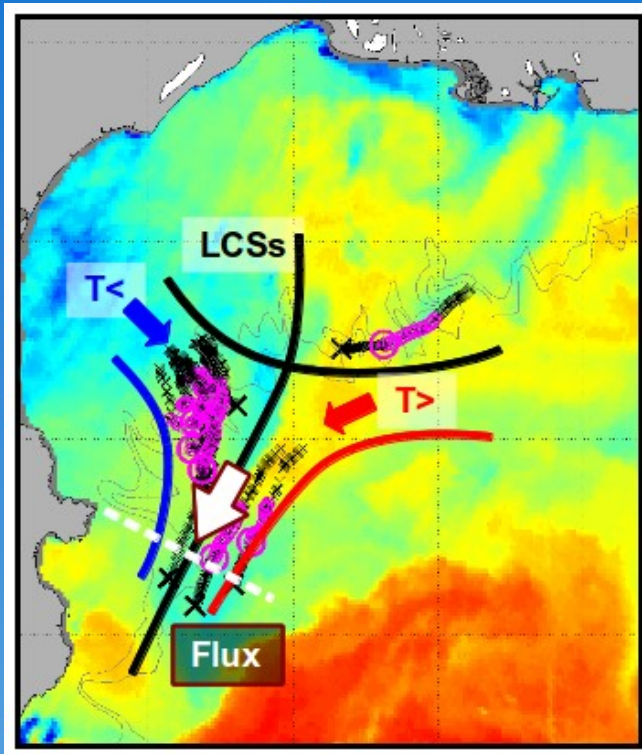


## → AVHRR SST + 3-day drifter trajectories (Sep. 8 to 15, 2010)

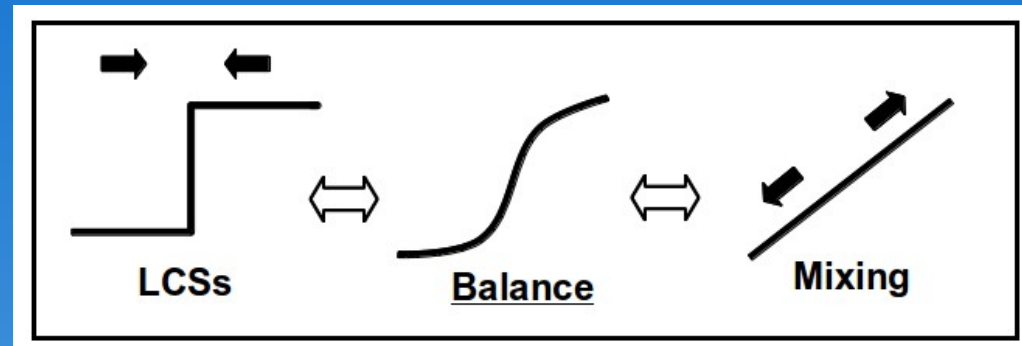
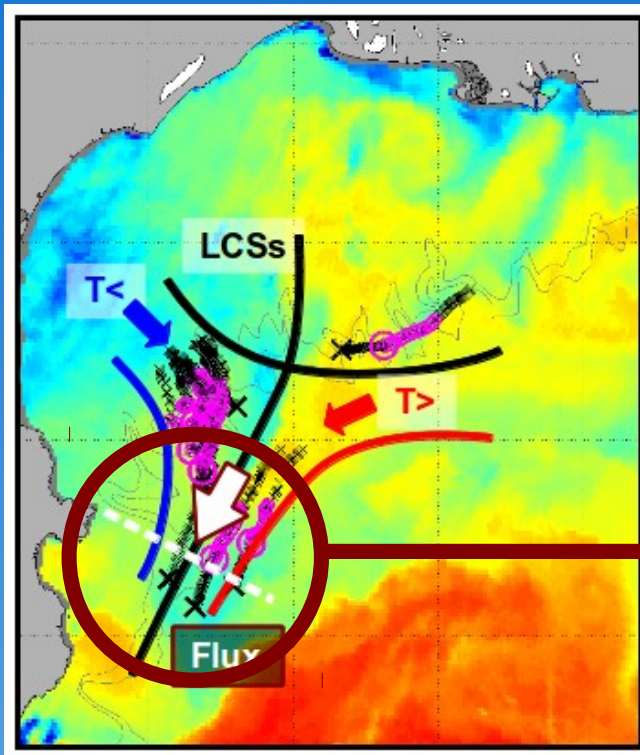


Convergence of warmer (eastern outer shelf) and colder (western inner shelf) water masses

→ Colder and warmer water masses converging along attractive LCS

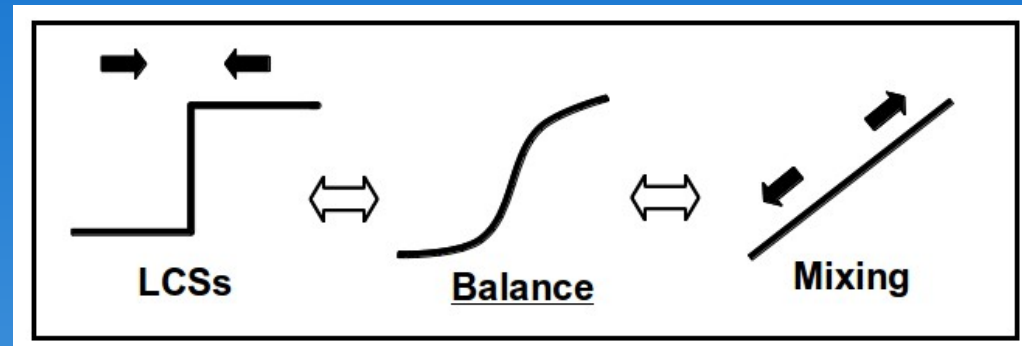
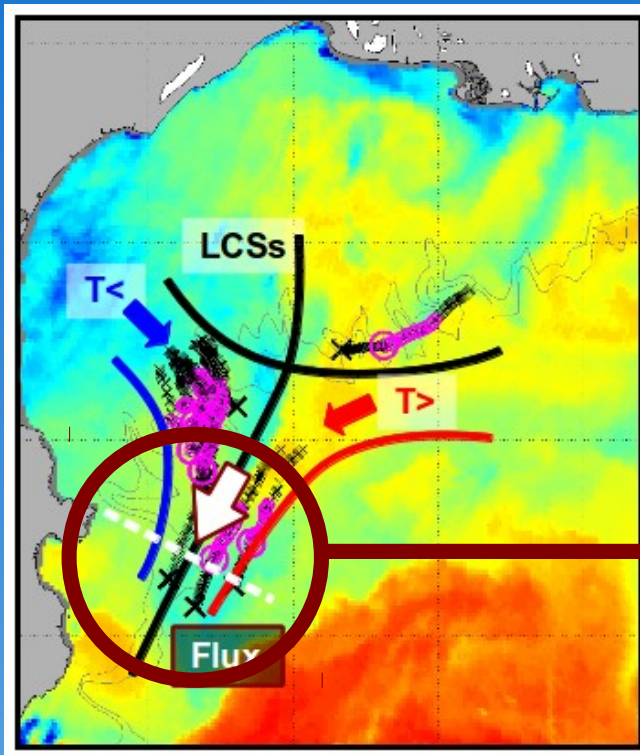


→ Colder and warmer water masses converging along attractive LCS



- Shape of T and S profile across the front results from balance between convergence and horizontal mixing

→ Colder and warmer water masses converging along attractive LCS



- Shape of  $T$  and  $S$  profile across the front results from balance between convergence and horizontal mixing

$$\frac{\partial T}{\partial t} + u(x) \frac{\partial T}{\partial x} = K_H \frac{\partial^2 T}{\partial x^2}$$

- Analytical solution to 1D advection diffusion equation for a tracer  $T$

→ Analogous to Flament et al. 1985, Ledwell et al. 1998 (from satellite)

## 1D equation for a tracer $T$

$$\frac{\partial T}{\partial t} + u(x) \frac{\partial T}{\partial x} = K_H \frac{\partial^2 T}{\partial x^2}$$

1D equation for a tracer  $T$ 

$$\cancel{\frac{\partial T}{\partial t}} + u(x) \frac{\partial T}{\partial x} = K_H \frac{\partial^2 T}{\partial x^2}$$



$$-\gamma(x - \mu) \frac{dT}{dx} = K_H \frac{d^2 T}{dx^2}$$

Assumptions:

- Front is at equilibrium (steady state)
- $x$  is the across LCS direction

1D equation for a tracer  $T$ 

$$\cancel{\frac{\partial T}{\partial t}} + u(x) \frac{\partial T}{\partial x} = K_H \frac{\partial^2 T}{\partial x^2}$$

$$-\gamma(x - \mu) \frac{dT}{dx} = K_H \frac{d^2 T}{dx^2}$$

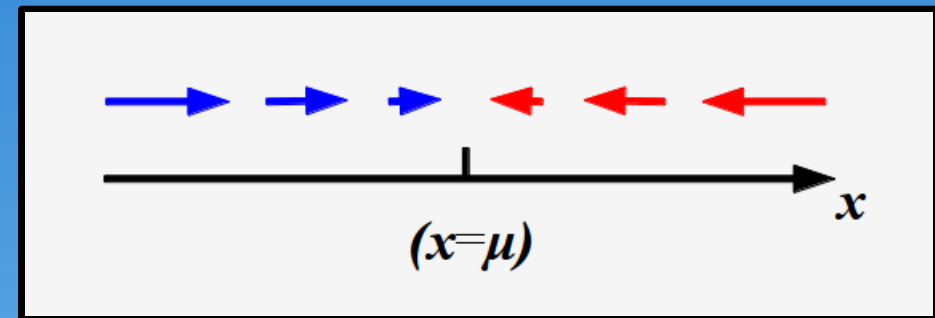
with

Assumptions:

- Front is at equilibrium (steady state)
- $x$  is the across LCS direction

$\gamma$  : Strain rate (Lyapunov exponent)

$\mu$  : Position of LCS axis



1D equation for a tracer  $T$ 

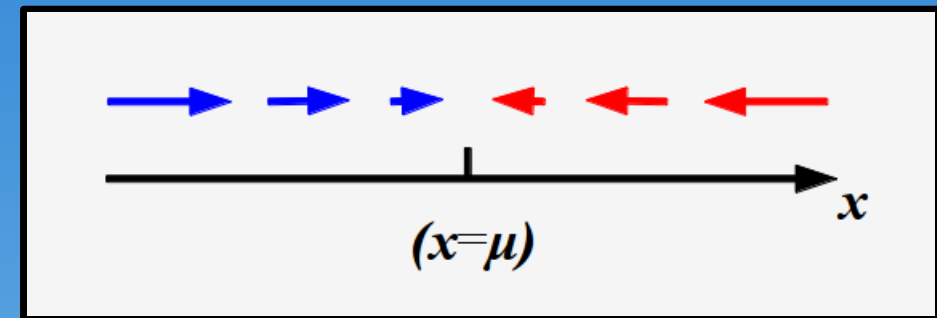
$$\cancel{\frac{\partial T}{\partial t}} + u(x) \frac{\partial T}{\partial x} = K_H \frac{\partial^2 T}{\partial x^2}$$

$$-\gamma(x - \mu) \frac{dT}{dx} = K_H \frac{d^2 T}{dx^2}$$

with

Assumptions:

- Front is at equilibrium (steady state)
- $x$  is the across LCS direction

 $\gamma$  : Strain rate (Lyapunov exponent) $\mu$  : Position of LCS axisBoundary Conditions

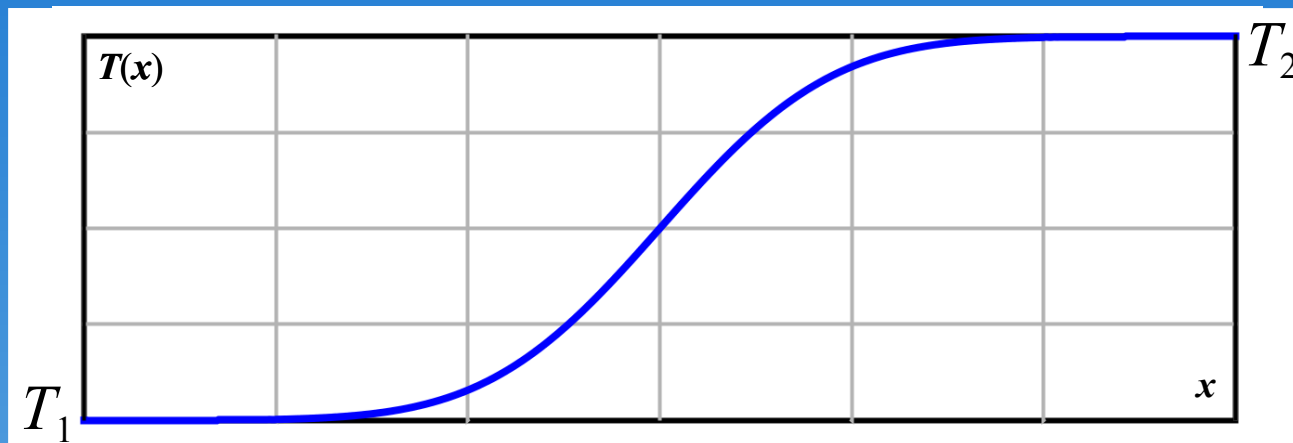
$$T(x = -\infty) = T_1;$$

$$T(x = +\infty) = T_2;$$

$$T(x) = \frac{T_2 + T_1}{2} + \frac{T_2 - T_1}{2} \operatorname{erf} \left( \frac{1}{\sqrt{2}} \sqrt{\frac{\gamma}{K_H}} (x - \mu) \right)$$



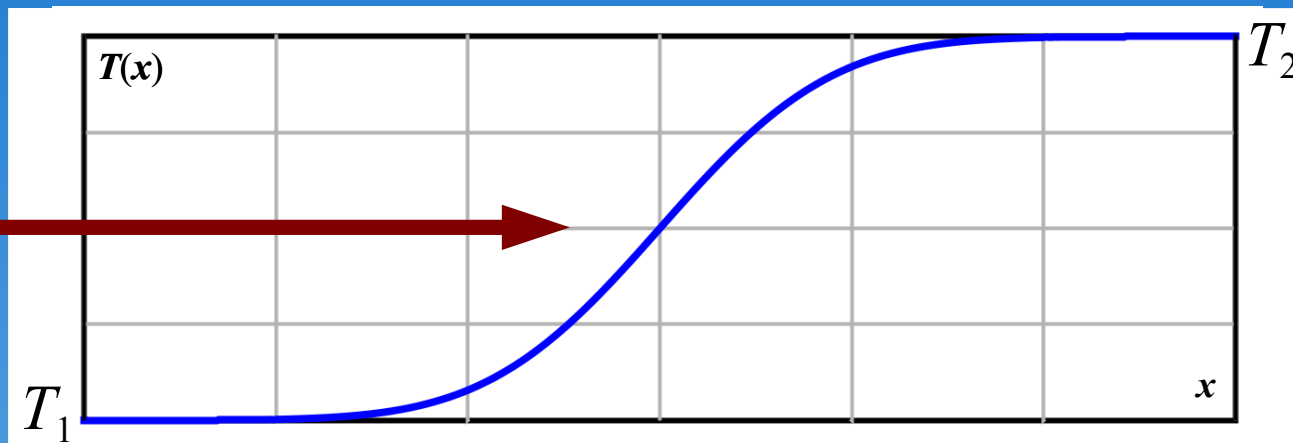
$$T(x) = \frac{T_2 + T_1}{2} + \frac{T_2 - T_1}{2} \operatorname{erf} \left( \frac{1}{\sqrt{2}} \sqrt{\frac{\gamma}{K_H}} (x - \mu) \right)$$



$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$$

$$T(x) = \underbrace{\frac{T_2 + T_1}{2}}_{C1} + \frac{T_2 - T_1}{2} \operatorname{erf}\left(\frac{1}{\sqrt{2}} \sqrt{\frac{\gamma}{K_H}} (x - \mu)\right)$$

C1

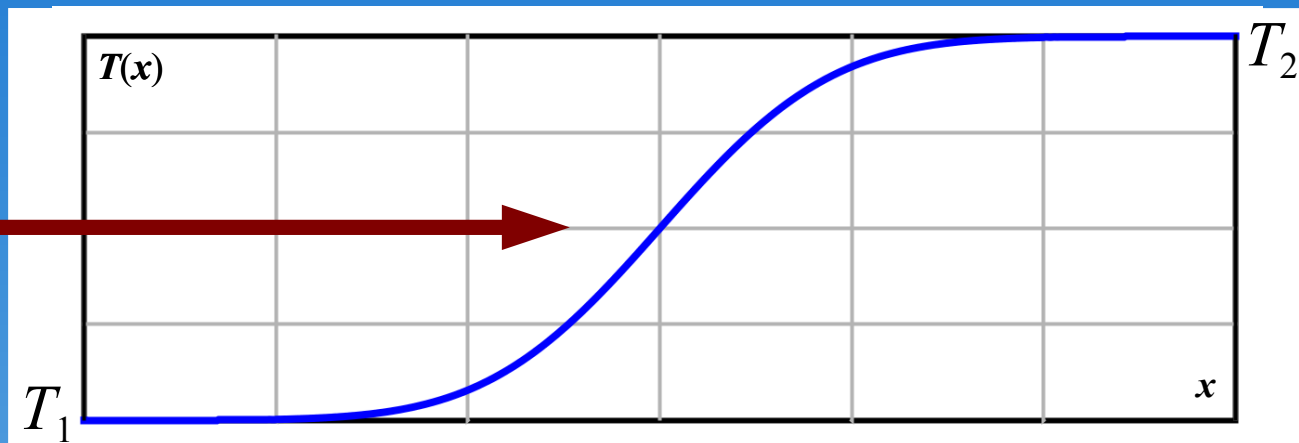


$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$$

$$T(x) = \underbrace{\frac{T_2 + T_1}{2}}_{C1} + \underbrace{\frac{T_2 - T_1}{2}}_{C2} \operatorname{erf} \left( \frac{1}{\sqrt{2}} \sqrt{\frac{\gamma}{K_H}} (x - \mu) \right)$$

C1

C2



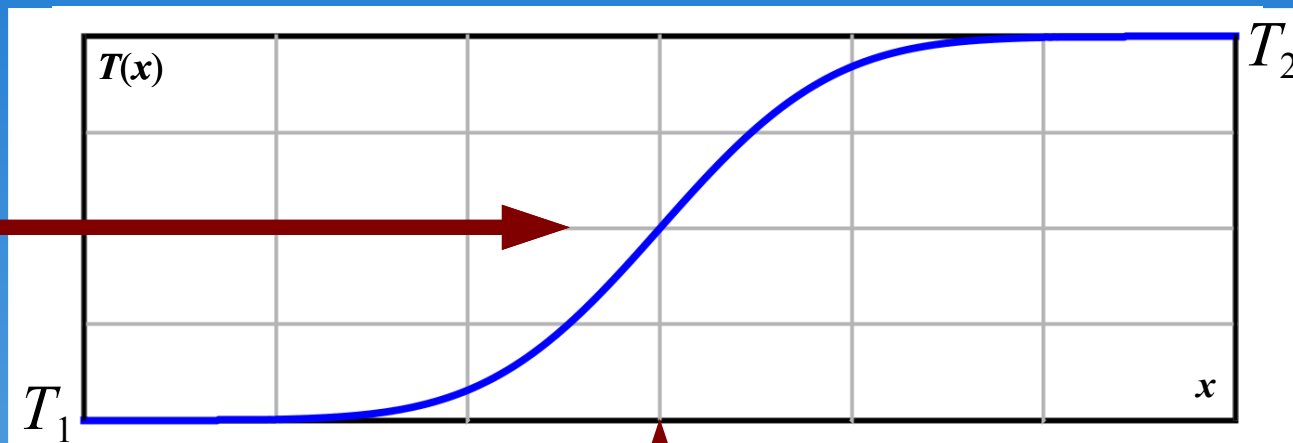
$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$$

$$T(x) = \underbrace{\frac{T_2 + T_1}{2}}_{C1} + \underbrace{\frac{T_2 - T_1}{2}}_{C2} \operatorname{erf} \left( \frac{1}{\sqrt{2}} \sqrt{\frac{\gamma}{K_H}} (x - \underbrace{\mu}_{C4}) \right)$$

C1

C2

C4



C1

C2

C4

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$$

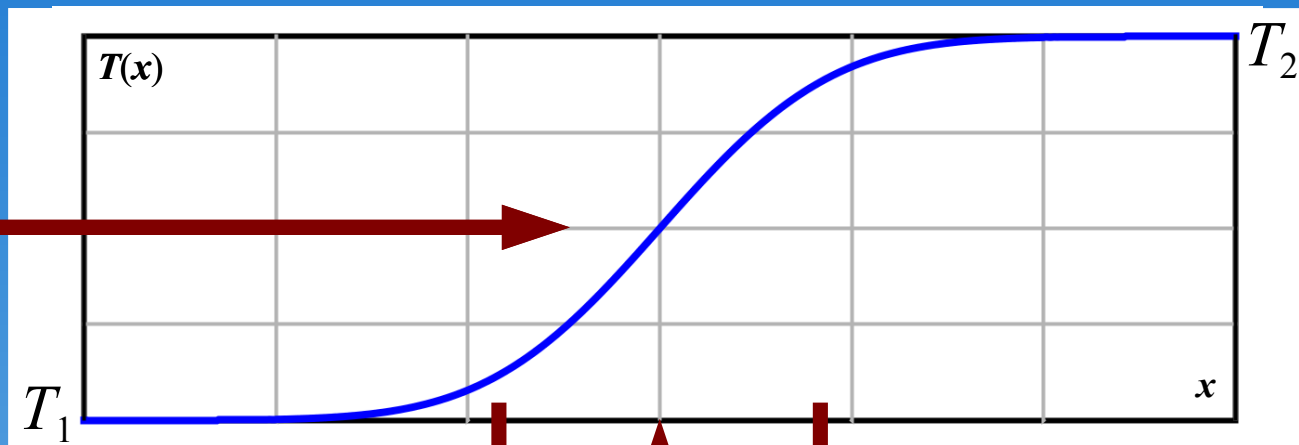
$$T(x) = \underbrace{\frac{T_2 + T_1}{2}}_{C1} + \underbrace{\frac{T_2 - T_1}{2}}_{C2} \operatorname{erf} \left( \underbrace{\frac{1}{\sqrt{2}} \sqrt{\frac{\gamma}{K_H}}}_{C3} \underbrace{(x - \mu)}_{C4} \right)$$

C1

C2

C3

C4



C1

C2

C3

C4

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$$

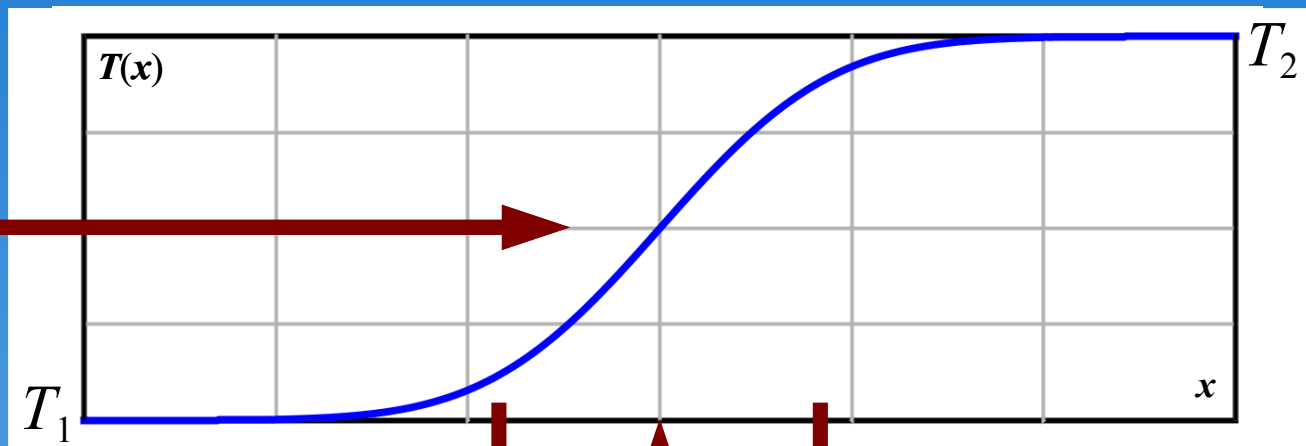
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C1

C2

C3

C4



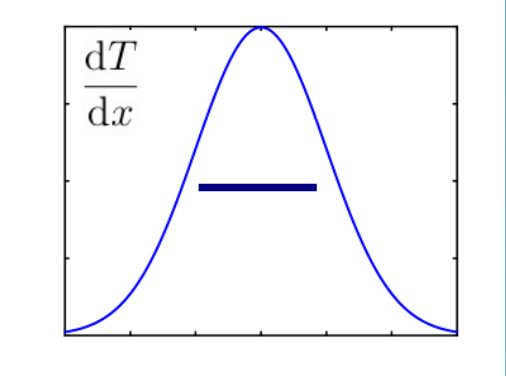
C1

C2

C3

C4

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$$



$$W_{front} = 2\sqrt{\frac{K_H}{\gamma}}$$

68% of T variation

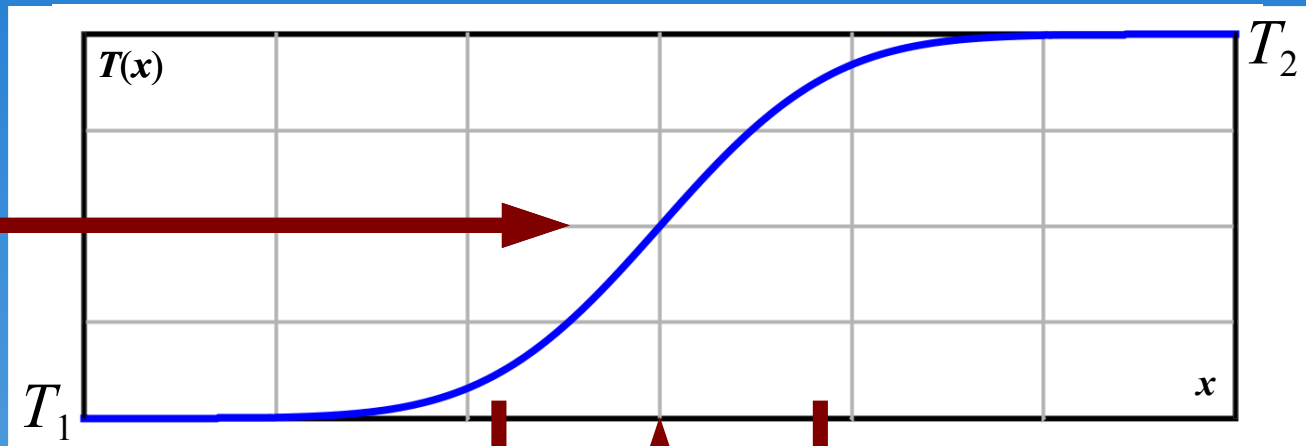
$$T(x) = \underbrace{\frac{T_2 + T_1}{2}}_{C1} + \underbrace{\frac{T_2 - T_1}{2}}_{C2} \operatorname{erf} \left( \underbrace{\frac{1}{\sqrt{2}} \sqrt{\frac{\gamma}{K_H}}}_{C3} (x - \underbrace{\mu}_{C4}) \right)$$

C1

C2

C3

C4



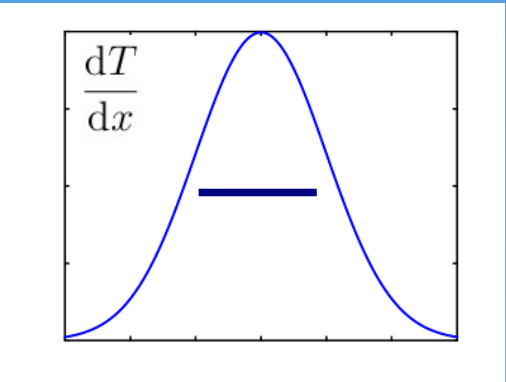
C1

C2

C3

C4

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$$



$$W_{front} = 2\sqrt{\frac{K_H}{\gamma}}$$

68% of T variation

- Coefficients computed by best fitting T and S sections

$$K_H = \frac{\gamma}{(2 C3^2)}$$

$$T(x) = \underbrace{\frac{T_2 + T_1}{2}}_{C1} + \underbrace{\frac{T_2 - T_1}{2}}_{C2} \operatorname{erf} \left( \underbrace{\frac{1}{\sqrt{2}} \sqrt{\frac{\gamma}{K_H}}}_{C3} (x - \underbrace{\mu}_{C4}) \right)$$

C1

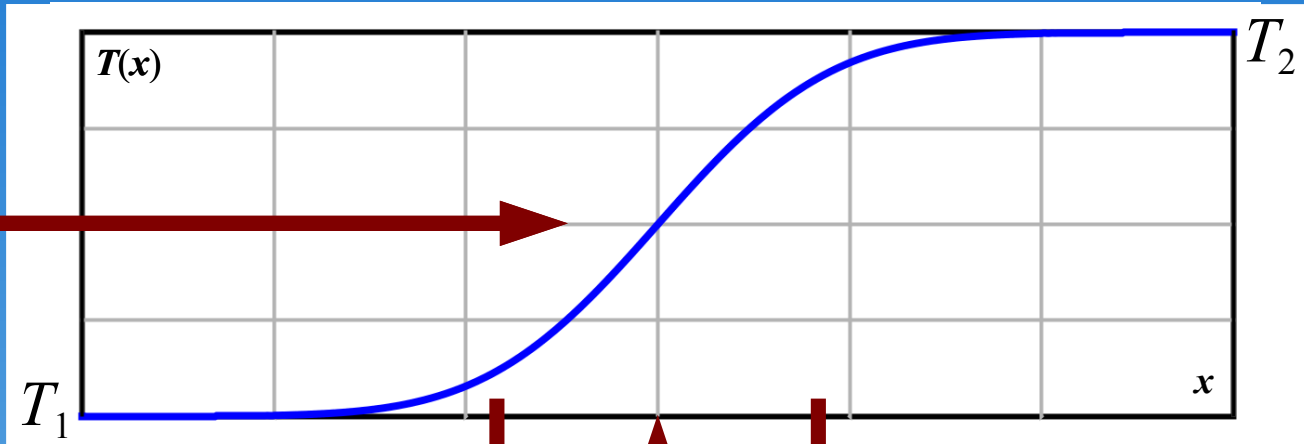
C2

C3

C4

C1

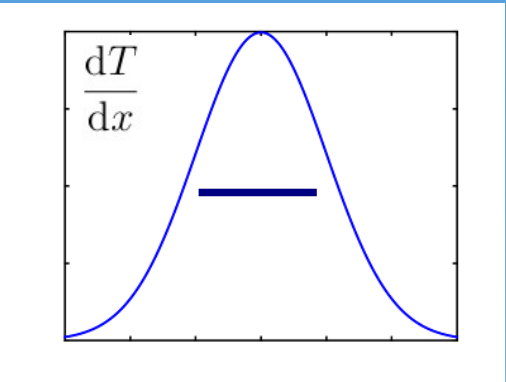
C2



$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$$

C3

C4



$$W_{front} = 2\sqrt{\frac{K_H}{\gamma}}$$

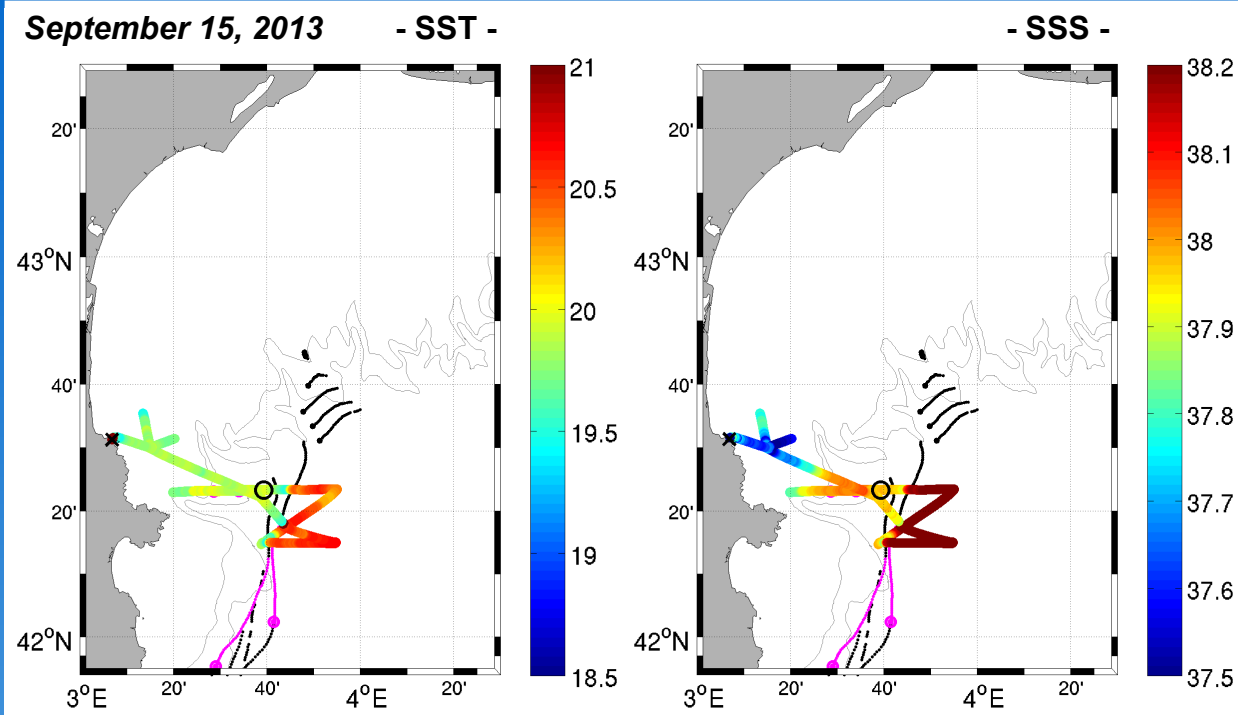
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- Coefficients computed by best fitting T and S sections

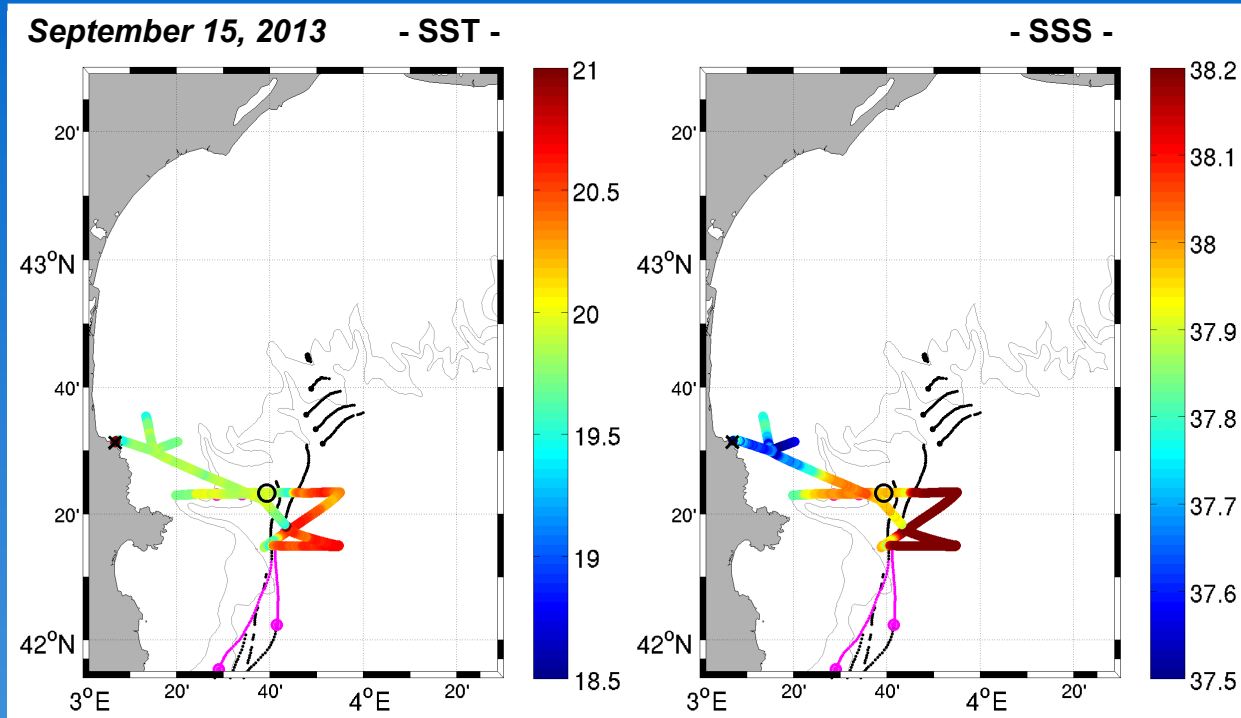
$$K_H = \frac{\gamma}{(2 C3^2)}$$

from drifter dispersion!!

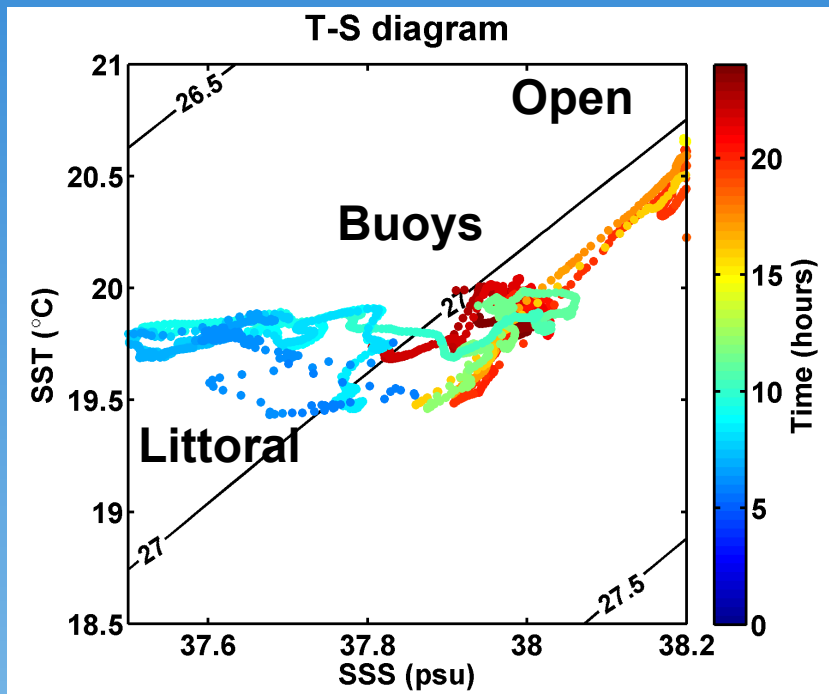


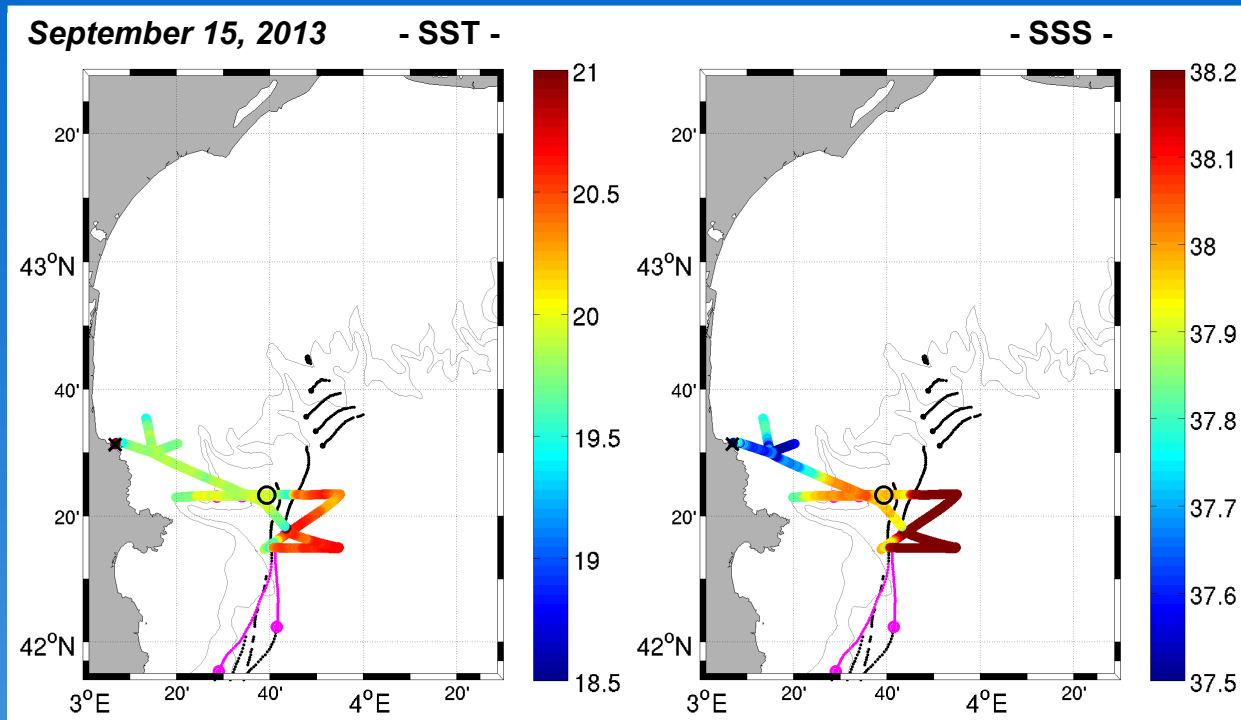


## SST and SSS from ship thermosalinograph

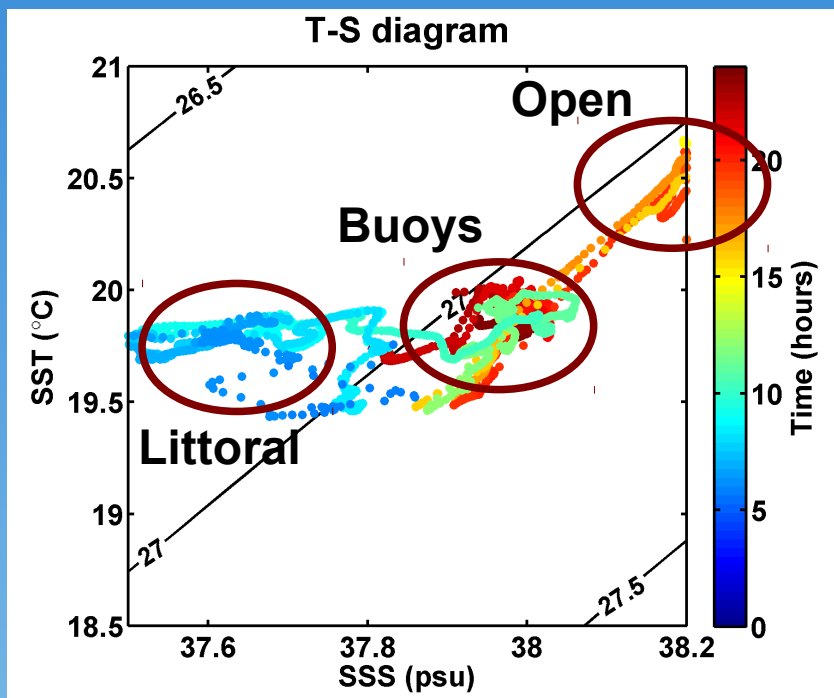


## SST and SSS from ship thermosalinograph





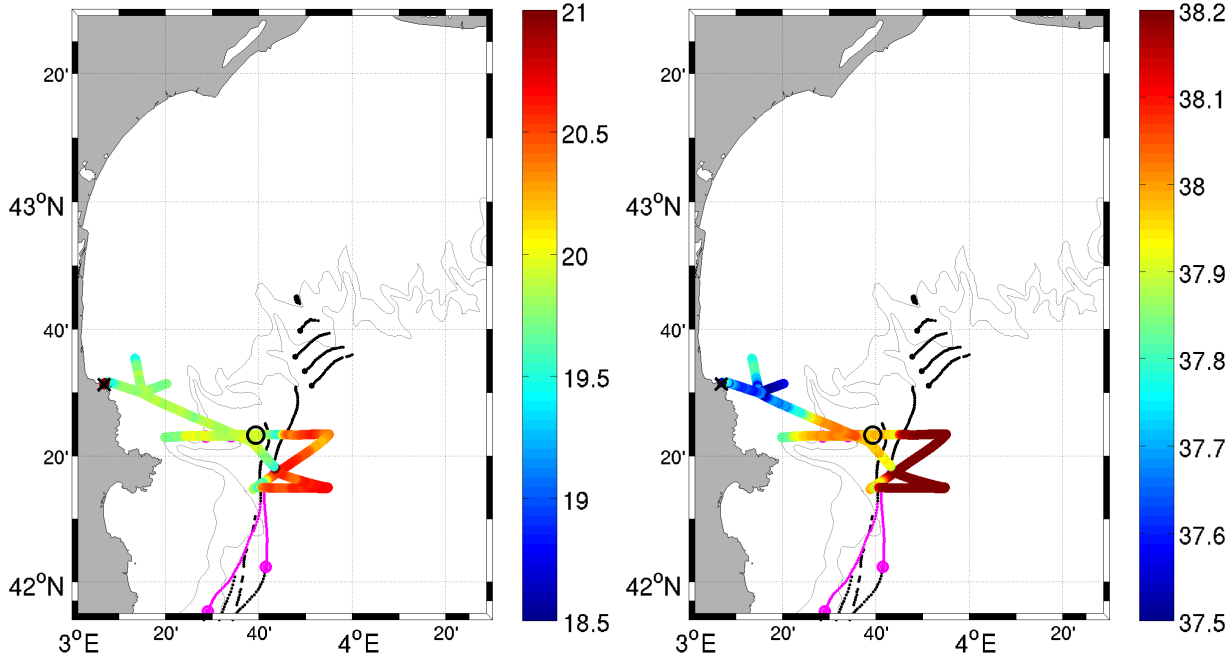
## SST and SSS from ship thermosalinograph



September 15, 2013

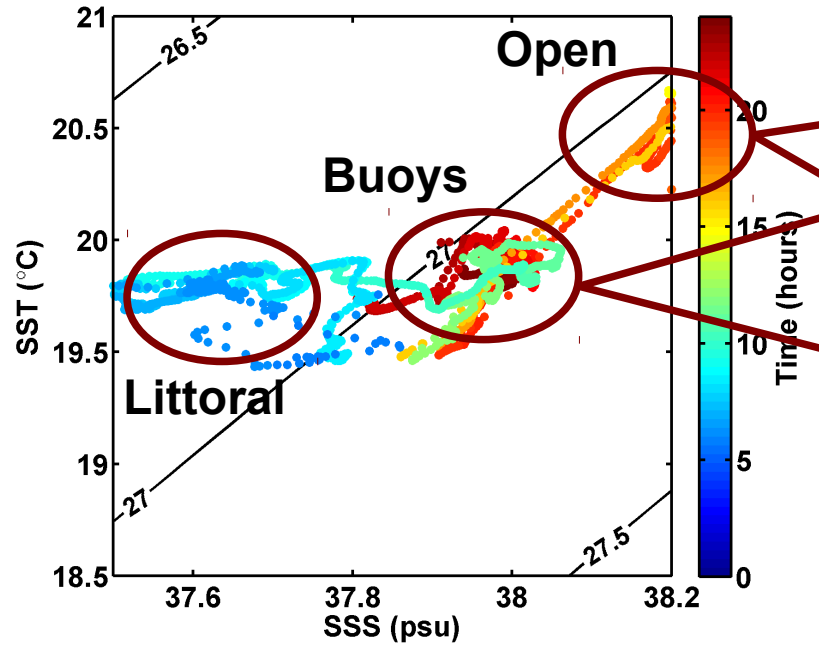
- SST -

- SSS -

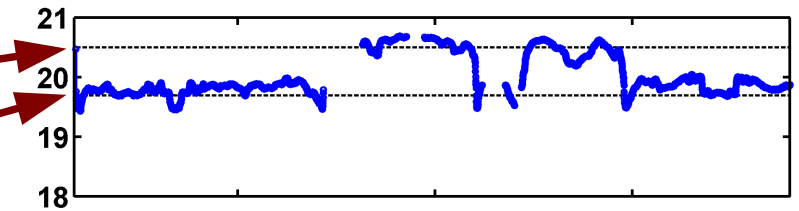


## SST and SSS from ship thermosalinograph

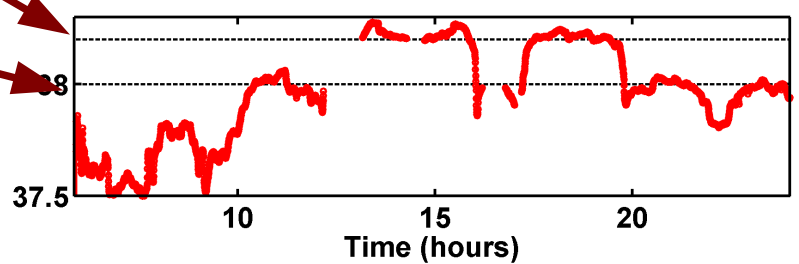
T-S diagram



SST t-series



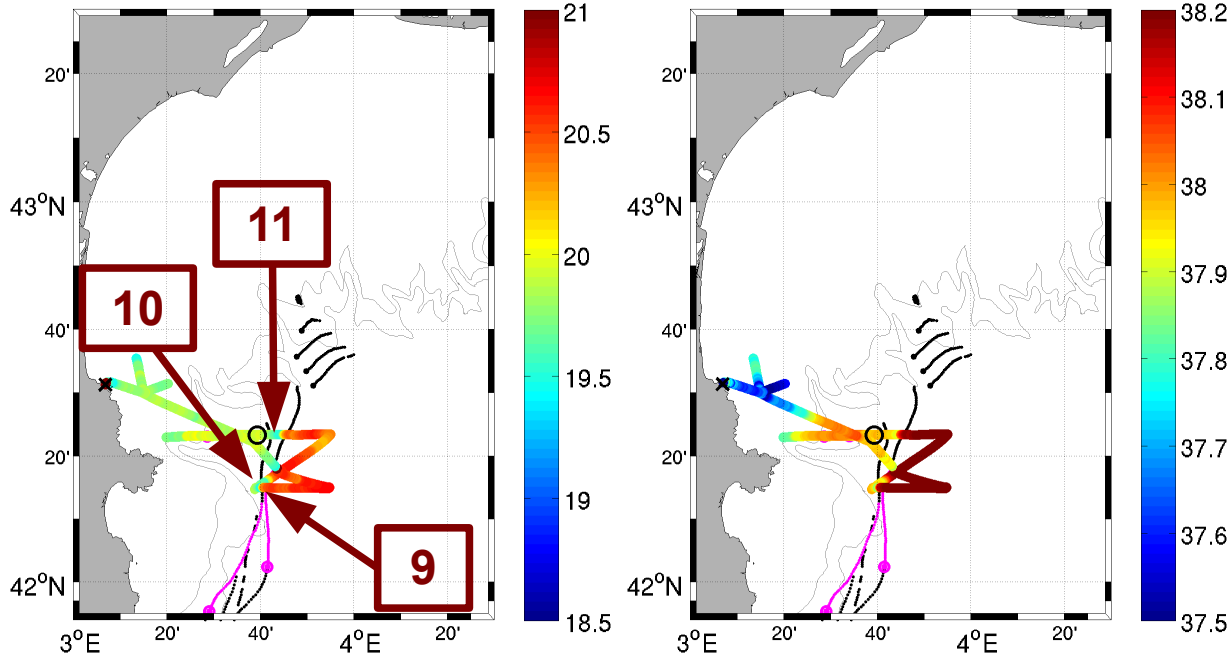
SSS t-series



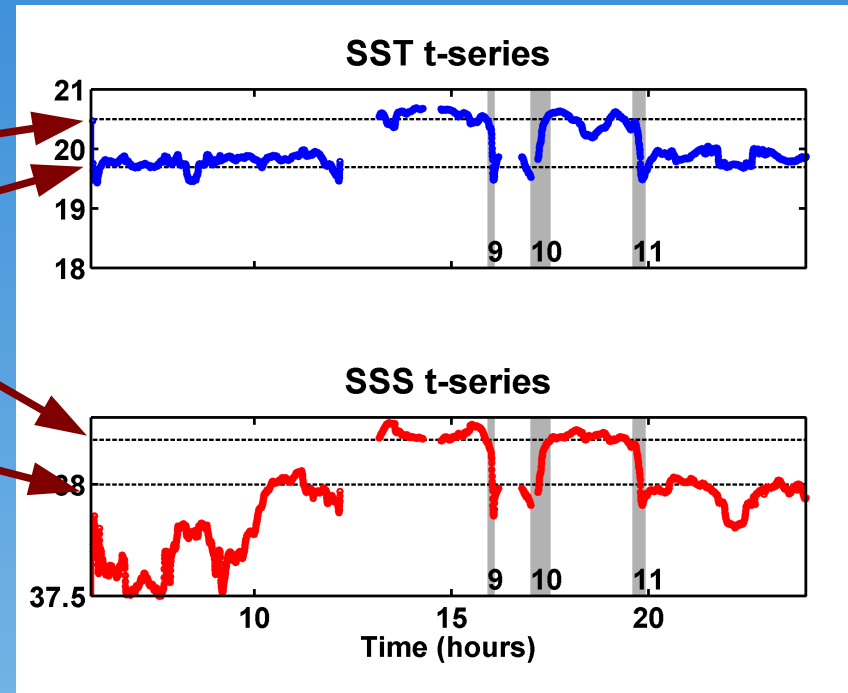
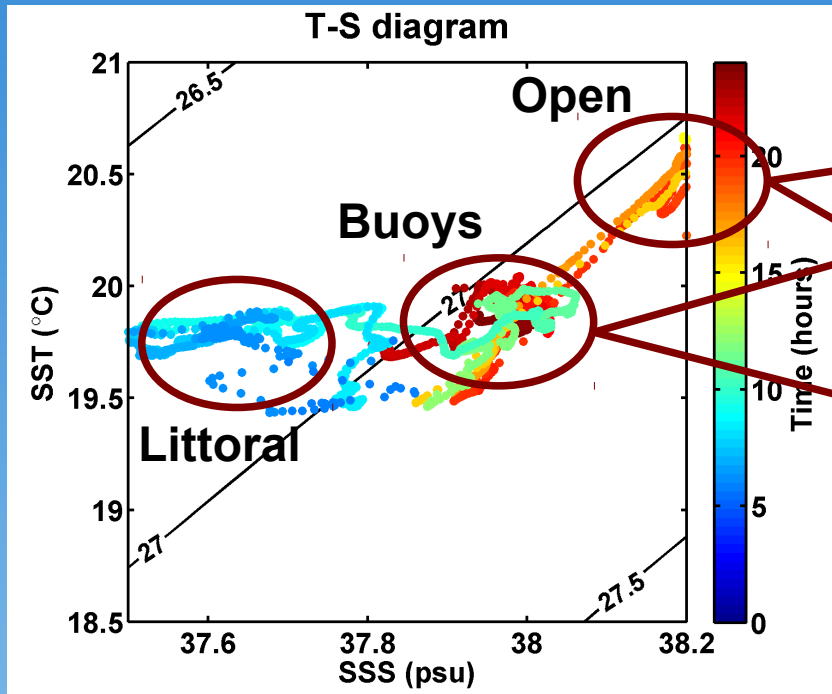
September 15, 2013

- SST -

- SSS -



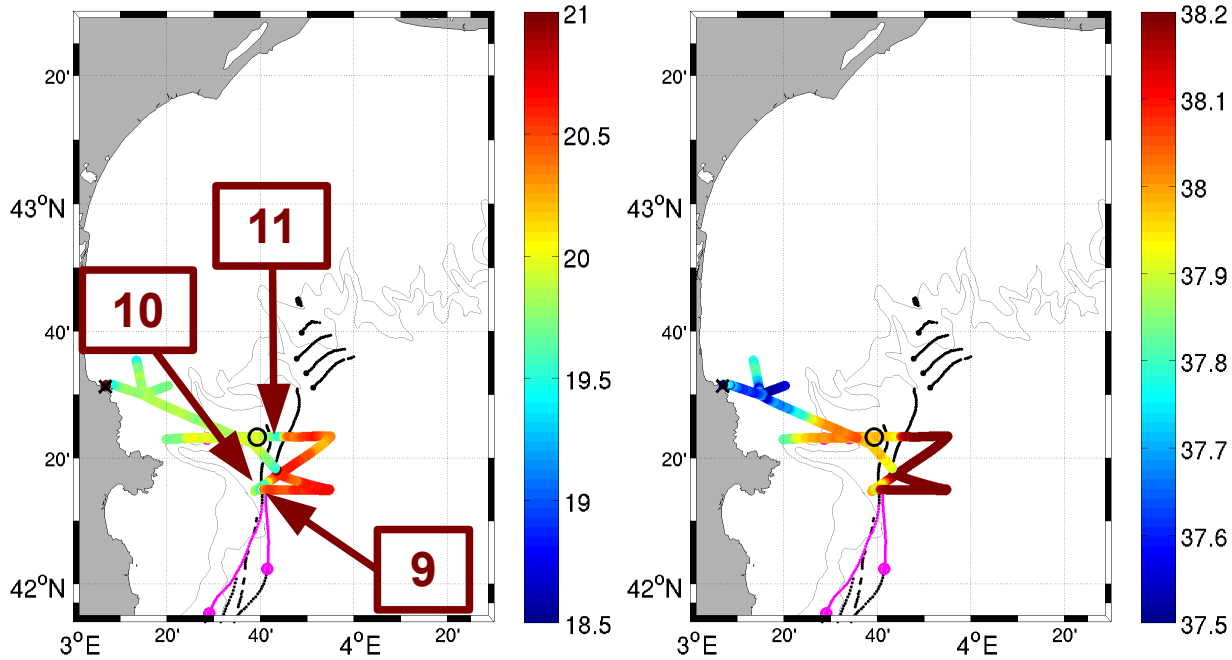
## SST and SSS from ship thermosalinograph



September 15, 2013

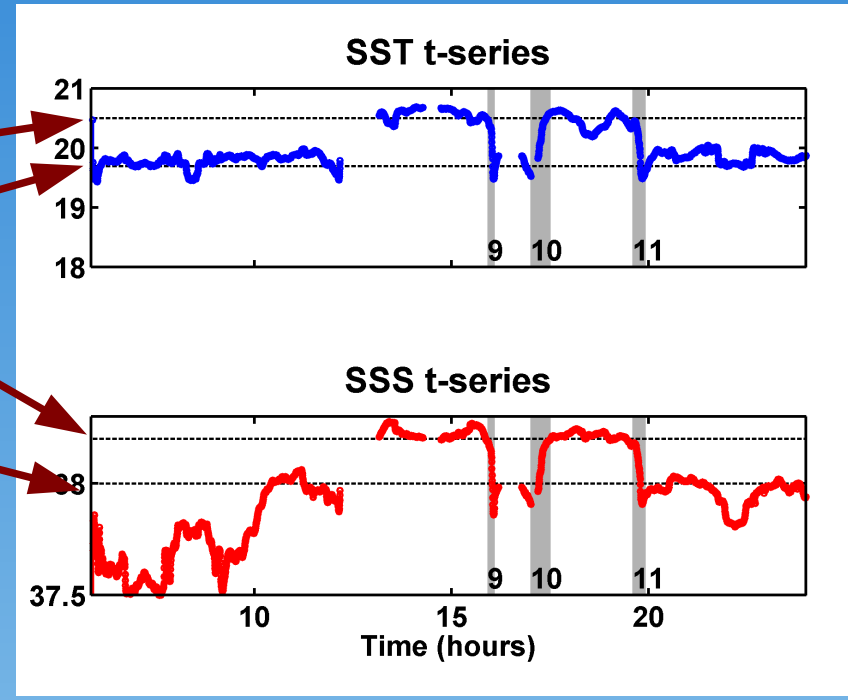
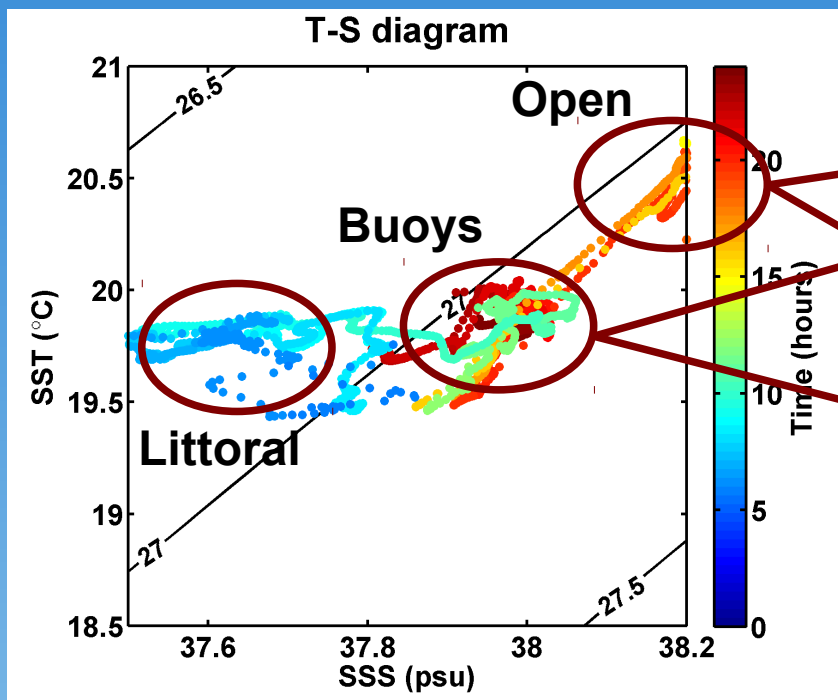
- SST -

- SSS -

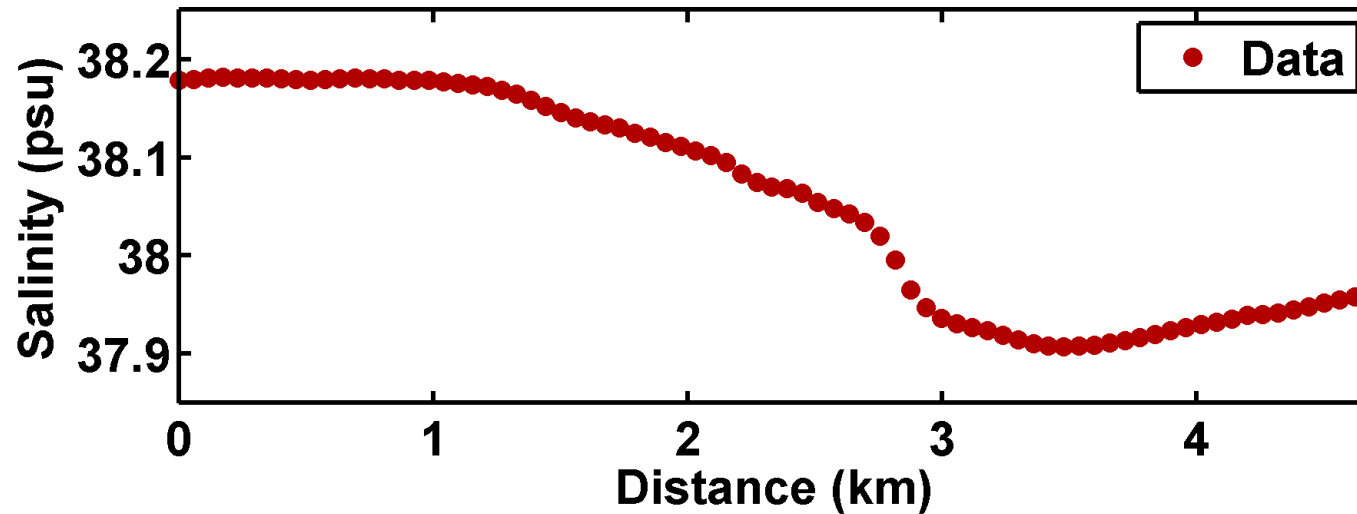
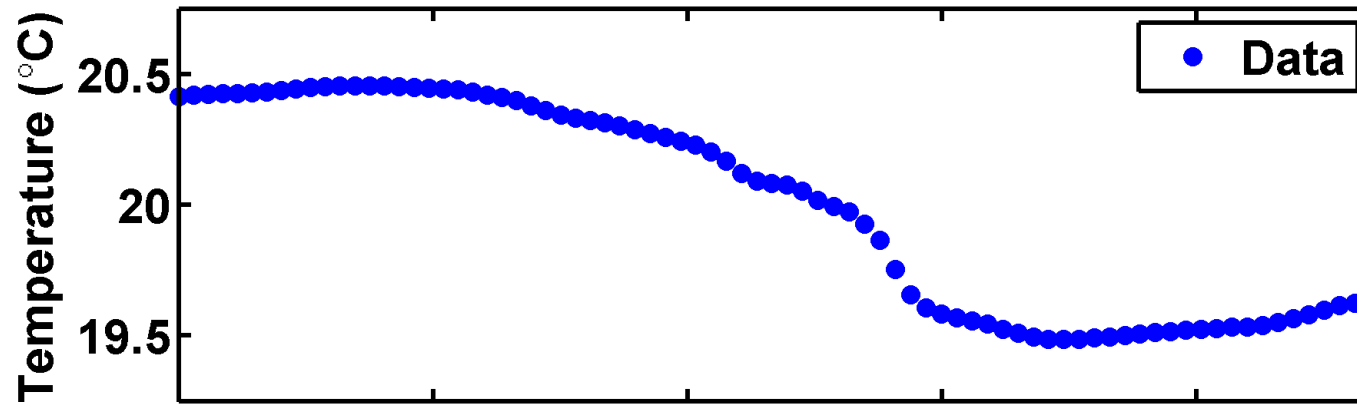


## SST and SSS from ship thermosalinograph

- Identified 30 cross-front transects
- Transects projected on the direction normal to the LCS axis



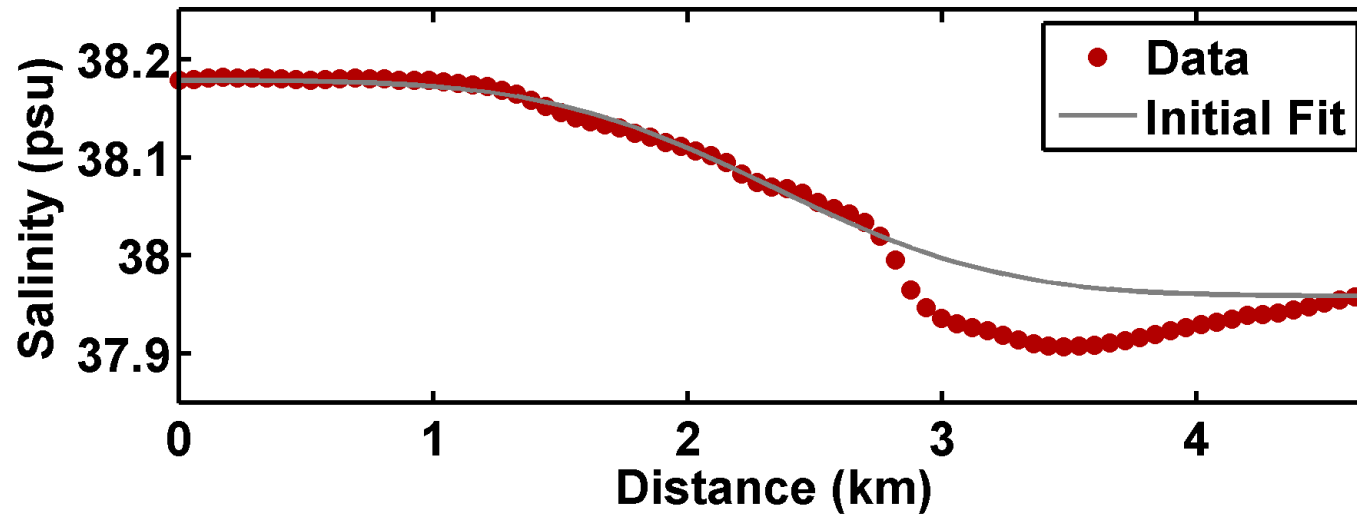
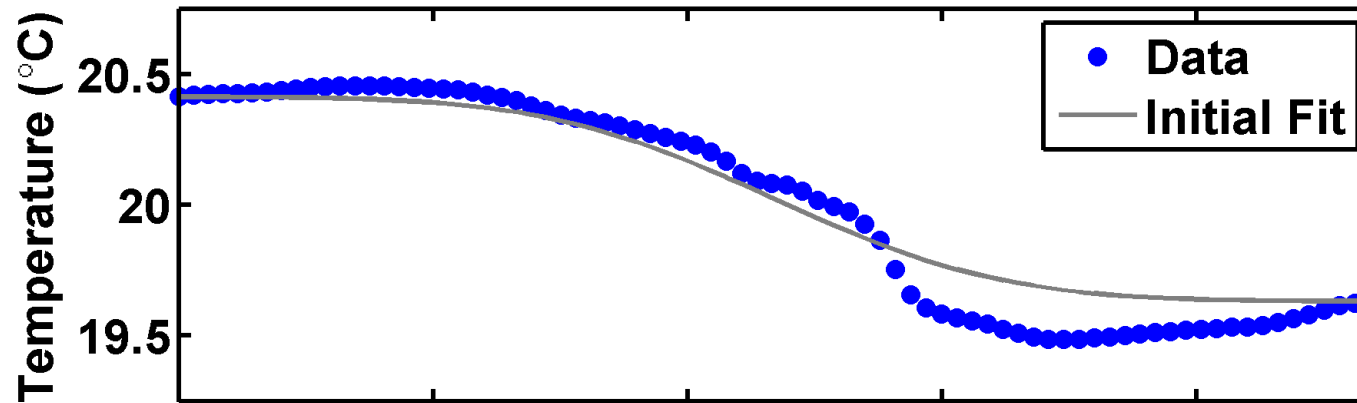
## Example: Transect 11



## Example: Transect 11

### Front equation

$$T(x) = C_1 + C_2 \operatorname{erf}(C_3 (x - C_4))$$



### Initial fit

$$C_1 = \frac{T_2 + T_1}{2}$$

$$C_2 = \frac{T_2 - T_1}{2}$$

$$C_3 = 1$$

$$C_4 = \frac{Dist}{2}$$

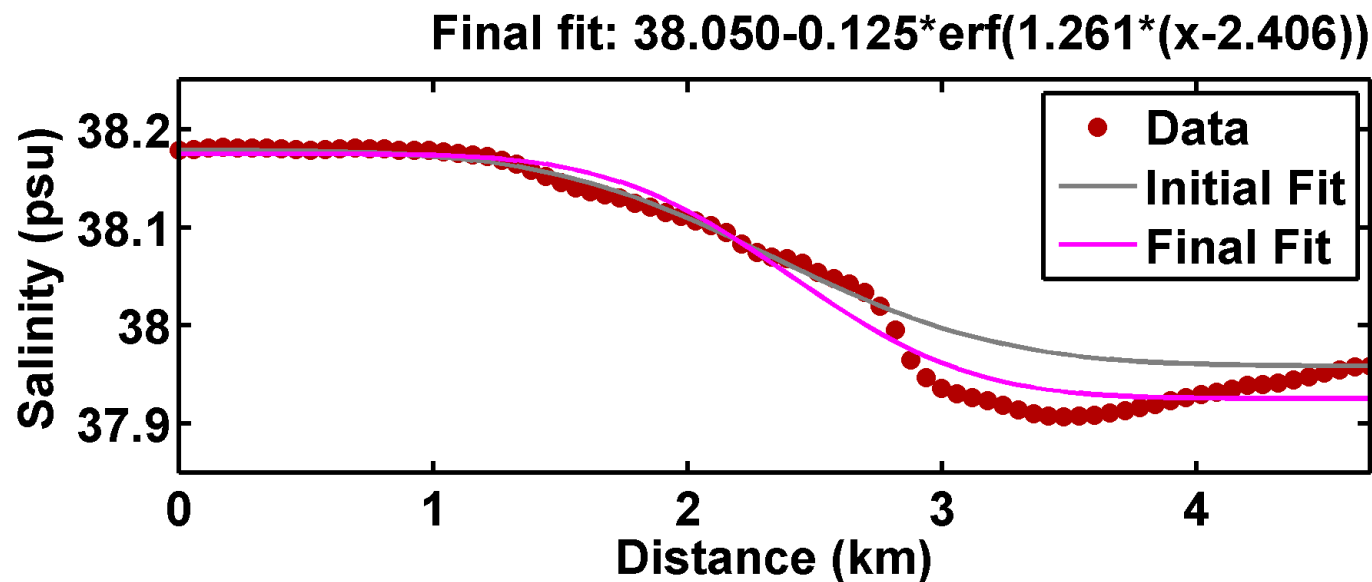
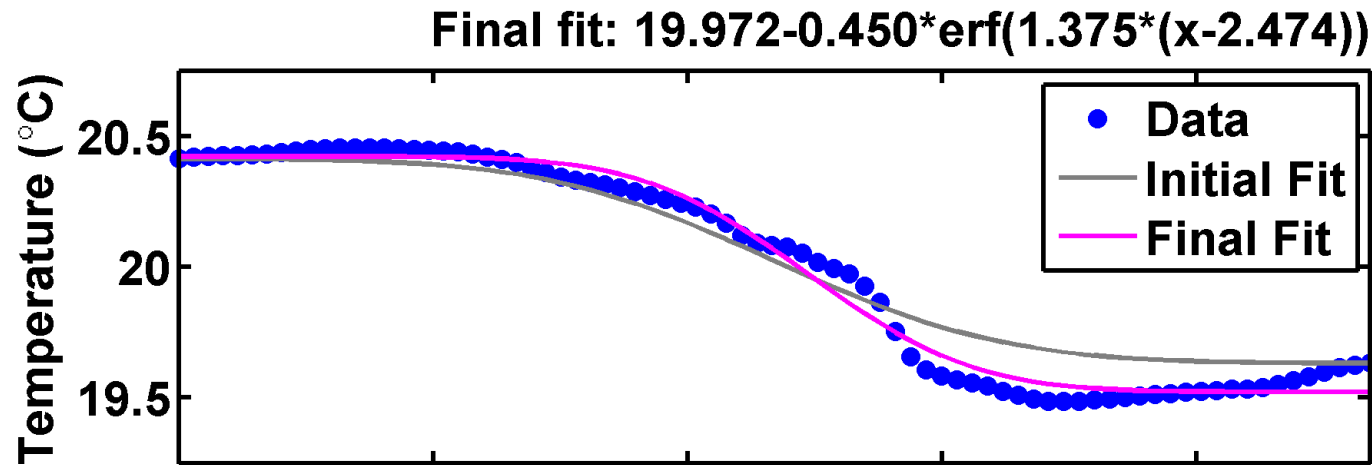


## Example: Transect 11

→ Parameters from least square estimation using Nelder-Mead simplex direct search

## Front equation

$$T(x) = C_1 + C_2 \operatorname{erf}(C_3 (x - C_4))$$

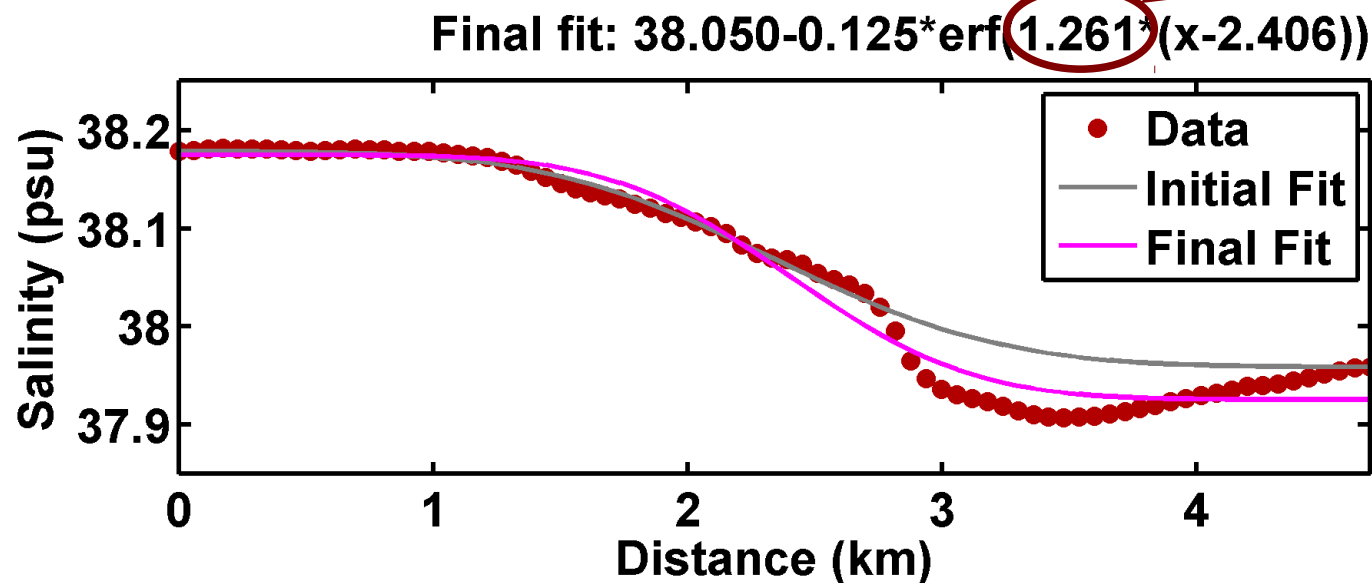
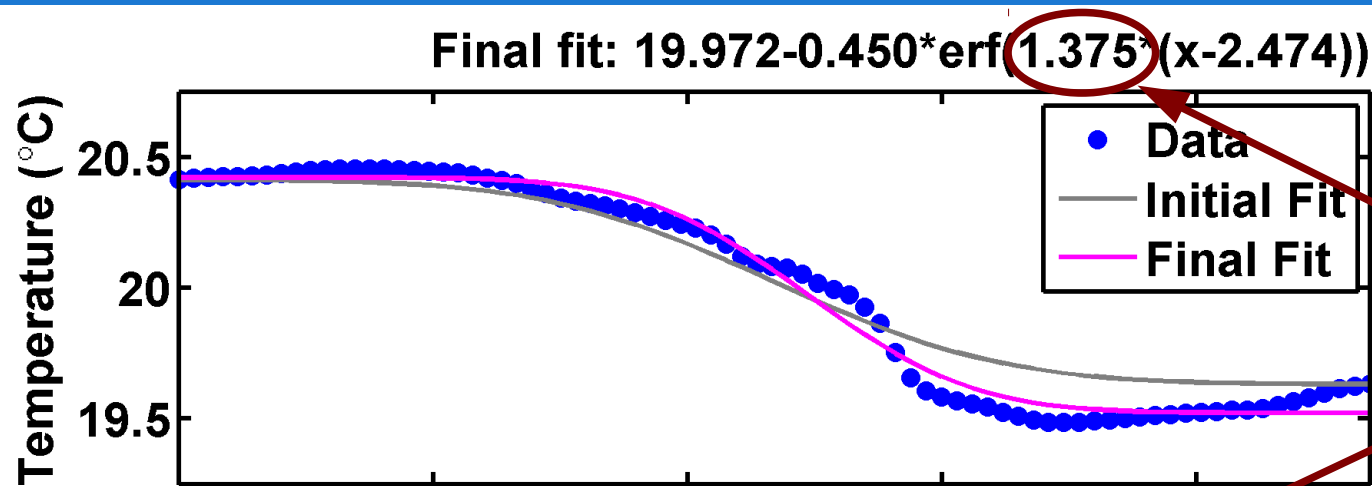


## Example: Transect 11

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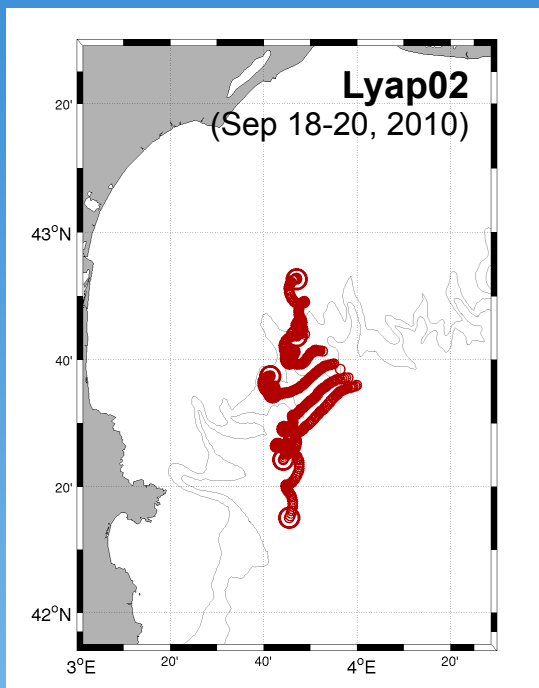
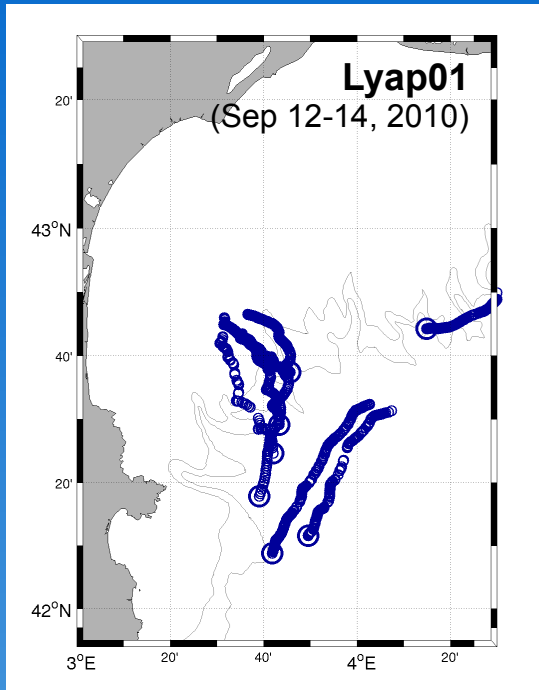


$$C_3 = \frac{1}{\sqrt{2}} \sqrt{\frac{\gamma}{K_H}}$$

- No fit for 11 out of 30 transects: limits of starting assumptions

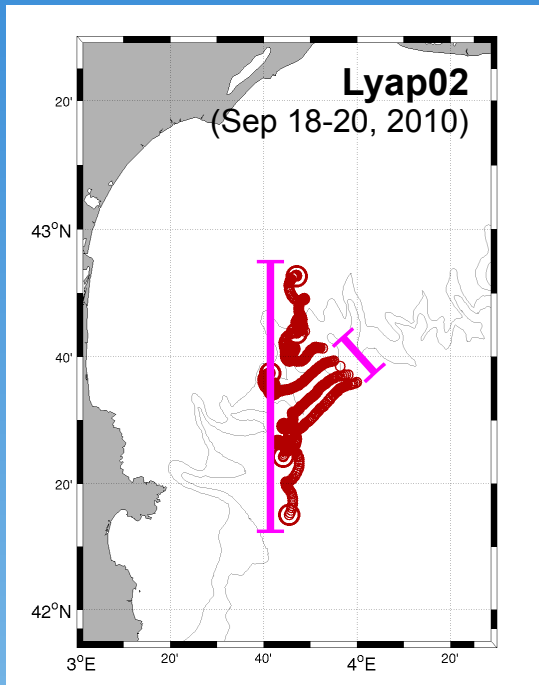
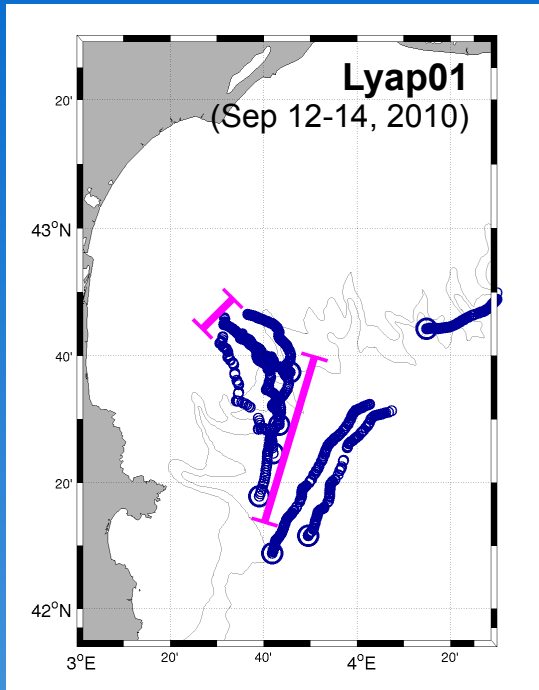
i.e. impact of vertical dynamics

## Dispersion patterns of drifter arrays



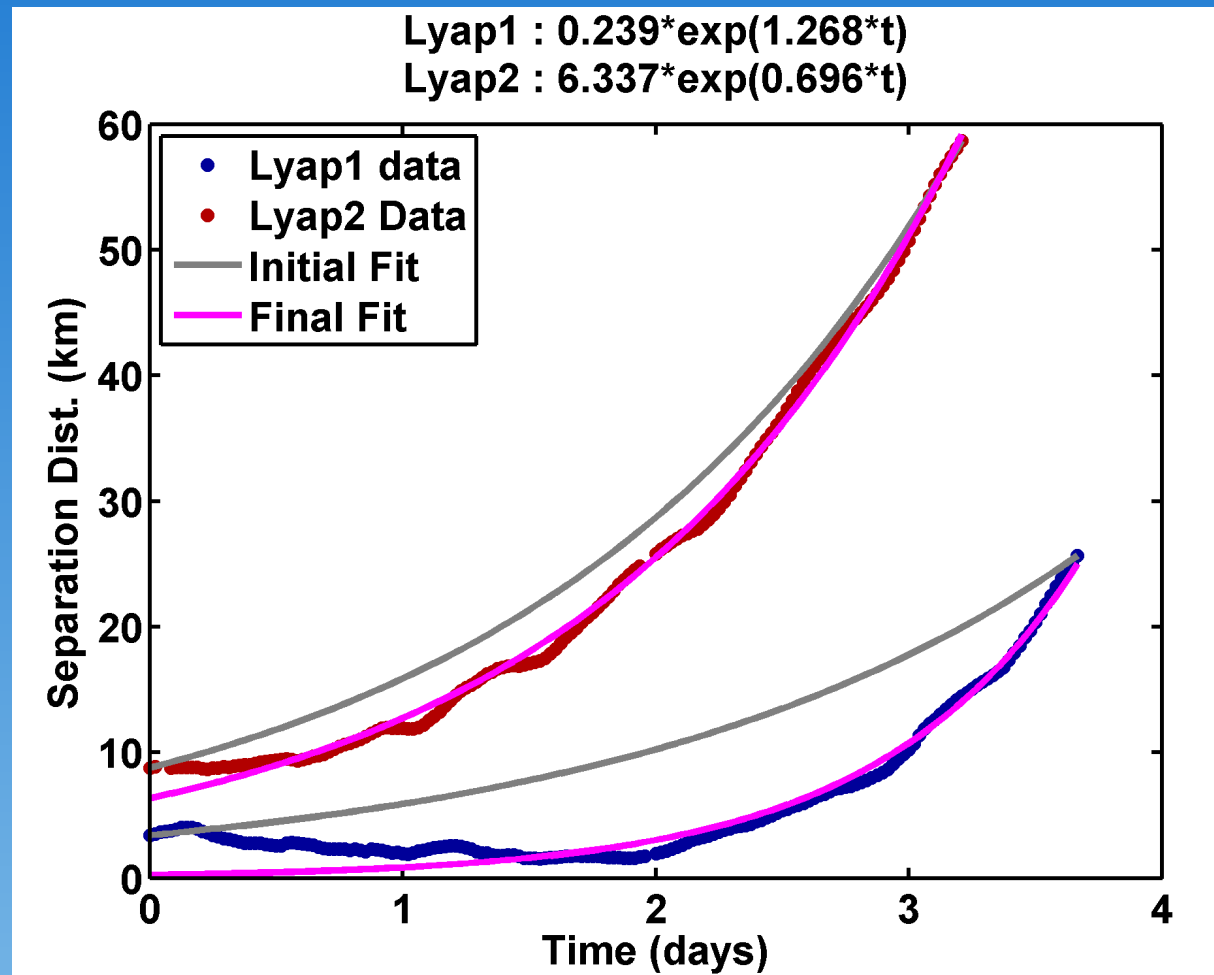
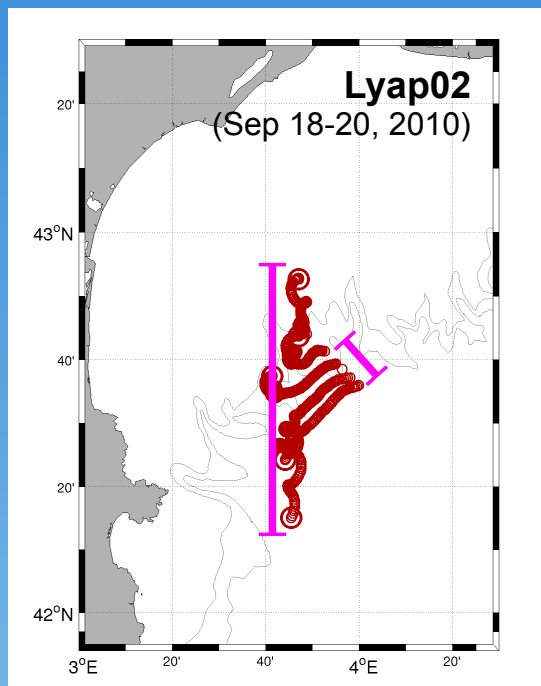
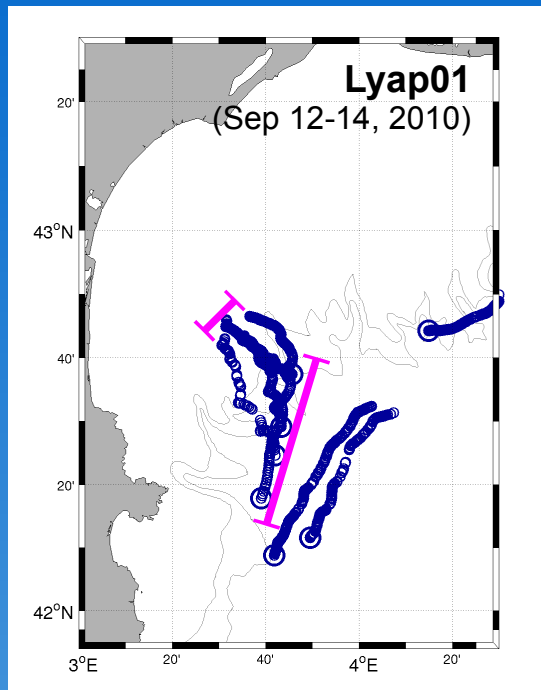
## Dispersion patterns of drifter arrays

- For each deployment, computed fastest separation rate between buoy couples (analogous to Lyapunov exponent)



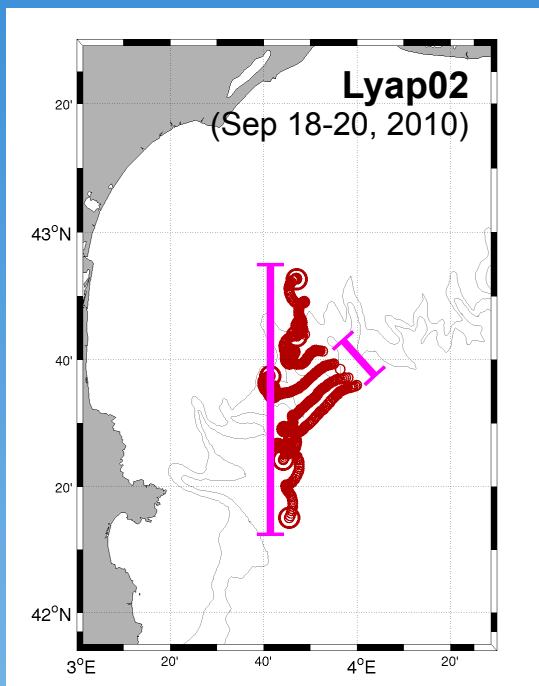
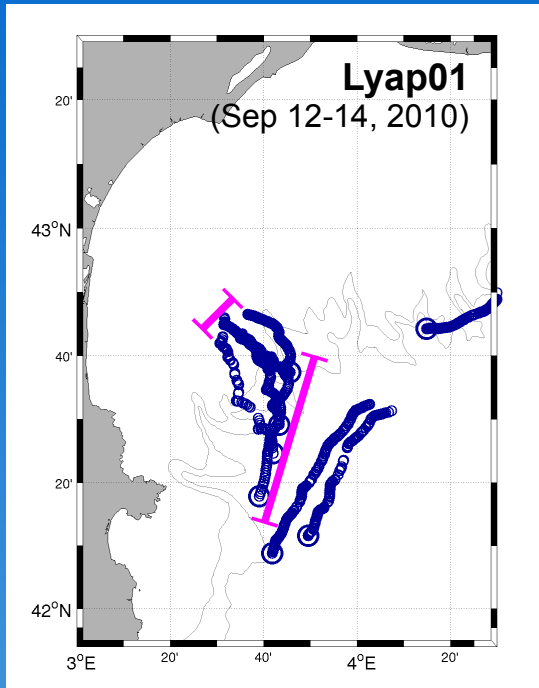
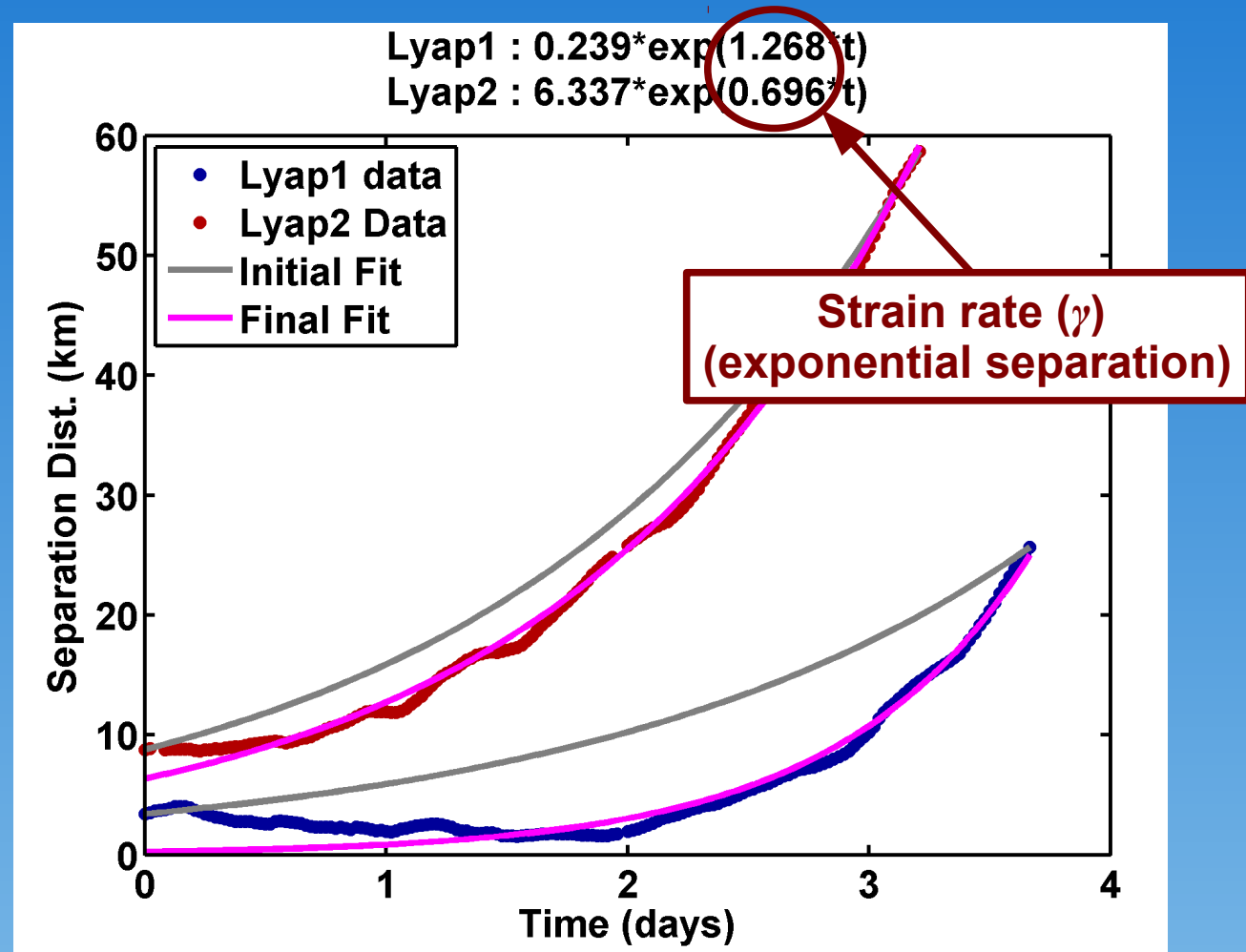
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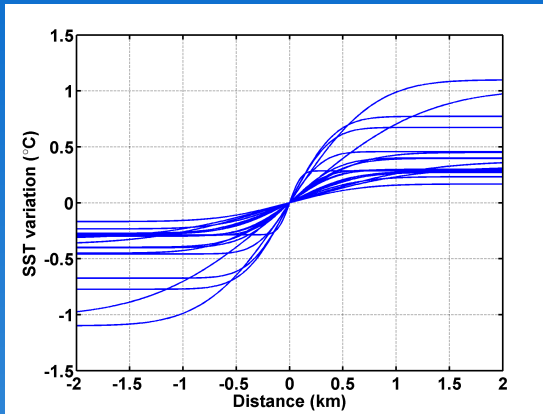


## Dispersion patterns of drifter arrays

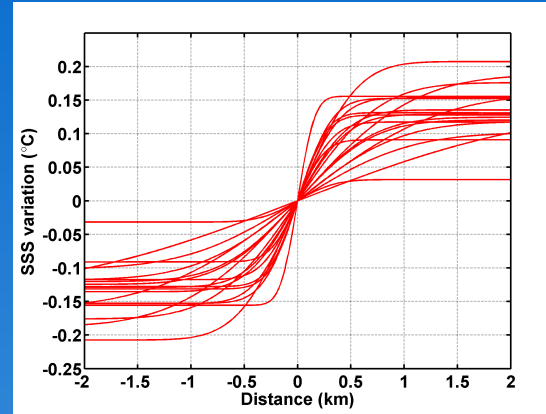
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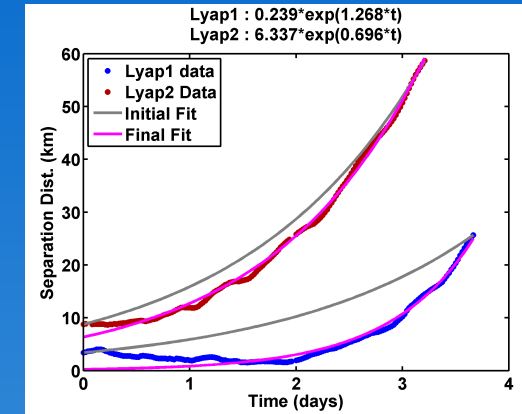
## T Front



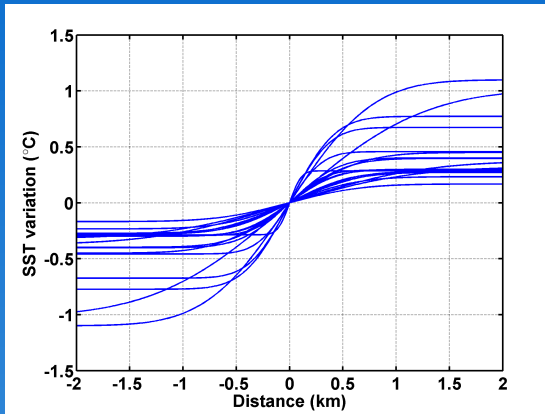
## S Front



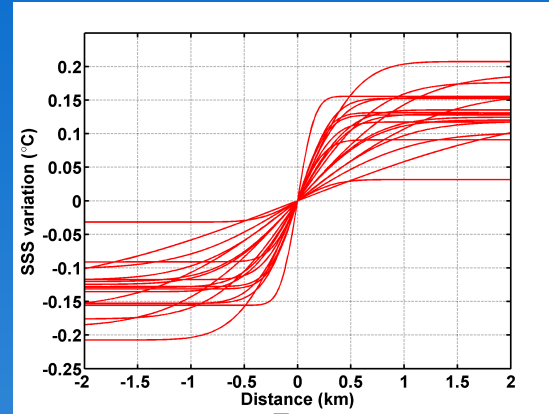
## Strain rate



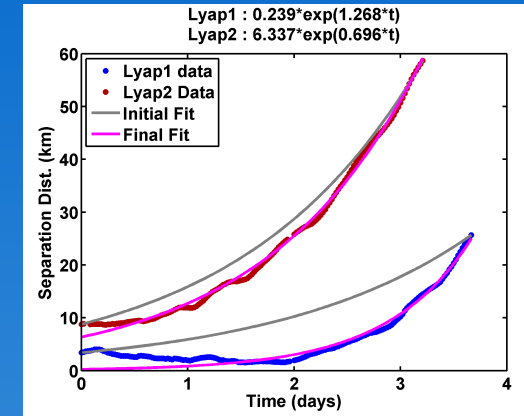
## T Front



## S Front

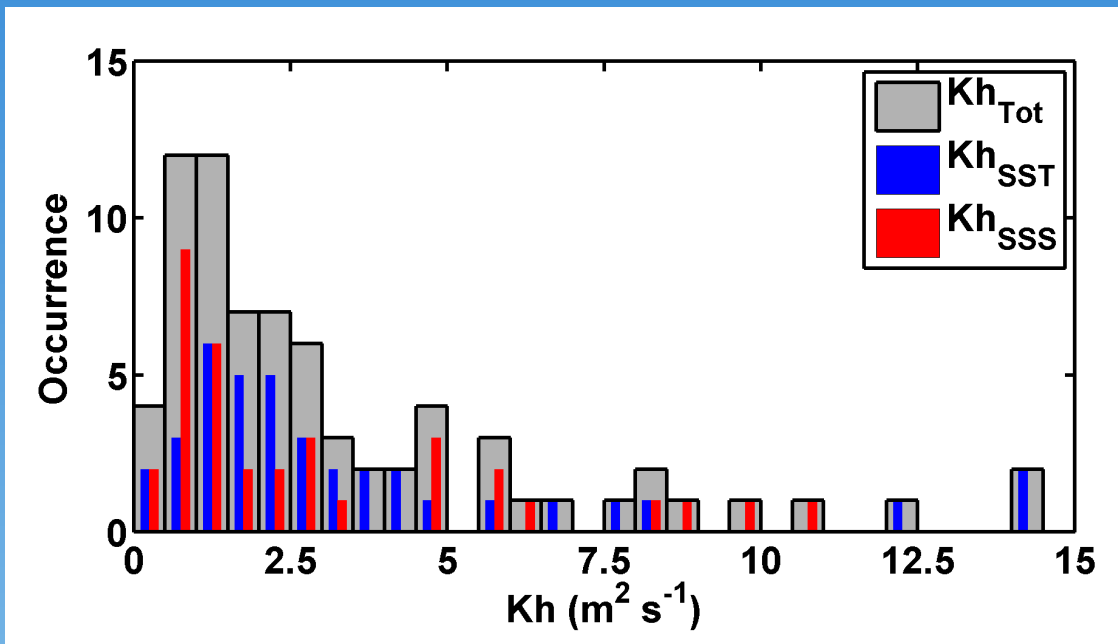


## Strain rate



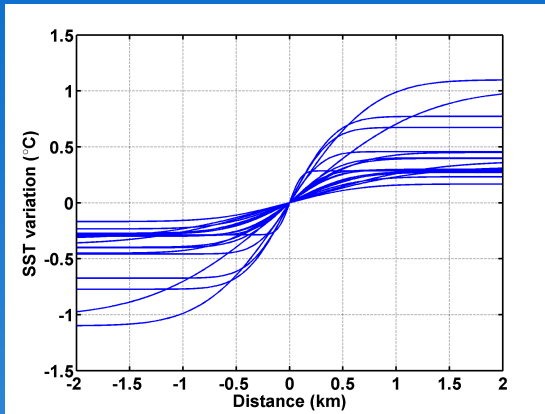
$$K_H = \frac{\gamma}{(2 C 3^2)}$$

## Eddy diffusivity coefficients

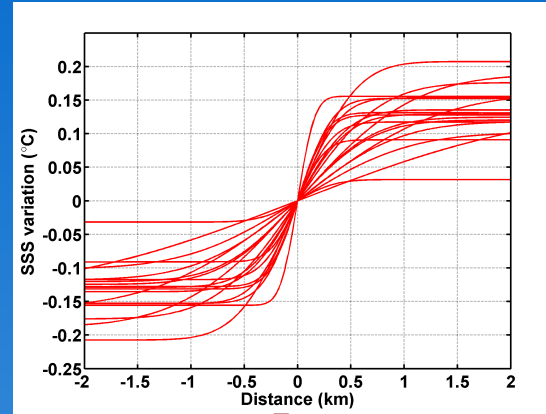




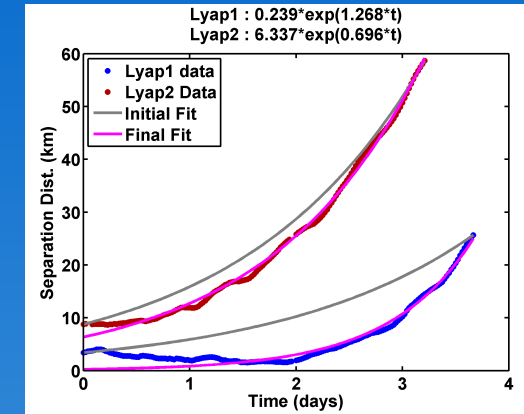
## T Front



## S Front

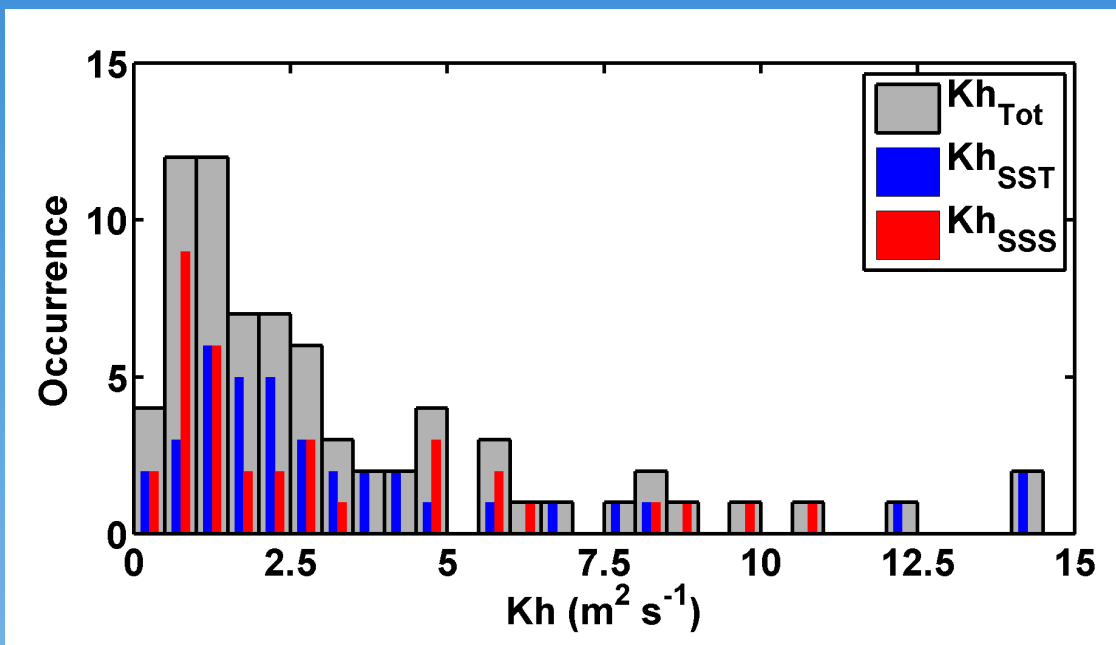


## Strain rate



$$K_H = \frac{\gamma}{(2 C 3^2)}$$

## Eddy diffusivity coefficients

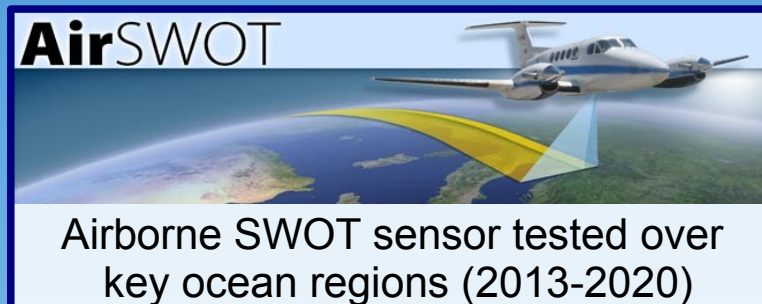


- $Kh_{SST}$  similar to  $Kh_{SSS}$
- 75% of estimates between  $0.5 - 5 \text{ m s}^{-2}$
- Front widths range from 250 m to 2km
- Long tail

- **New approach relatively simple and cheap**  
(i.e. compared to passive tracer release experiments)
  
- **In-situ estimates of  $K_h$  at the submesoscale in line with values used in high-resolution numerical models**
  
- **Tail of high values affects  $K_h$  statistics (mean and standard deviation) => check starting assumptions:**
  - **Steady state**
  - **Uniform strain rate**
  - **Vertical motions**
  - **...**

- Further dedicated in-situ experiments
- Test approach from high-resolution models
- Extend analysis of  $K_h$  over wider regions/the global ocean using remote sensed datasets

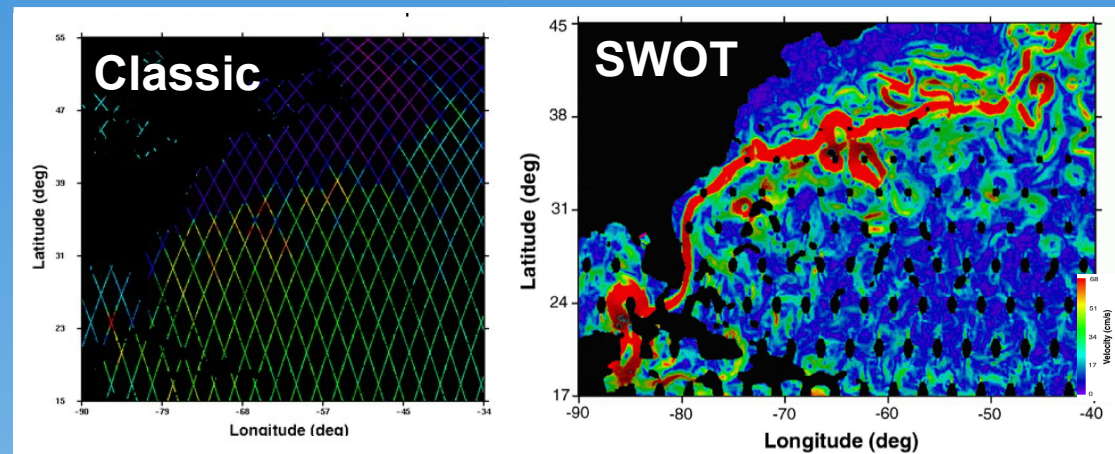
- Further dedicated in-situ experiments
- Test approach from high-resolution models
- Extend analysis of Kh over wider regions/the global ocean using remote sensed datasets



## Surface Water and Ocean Topography

*NASA – CNES mission*

- New generation, high-resolution (1Km) altimeter
- Launch: Fall 2020



This work has been developed within the project:



## Lyapunov Analysis in the CoaSTal Environment (LACOSTE)

**Marie Curie Intra-European Fellowship**  
**Call: FP7 - PEOPLE - 2011 - IEF**  
**Leading PI: F. Nencioli**

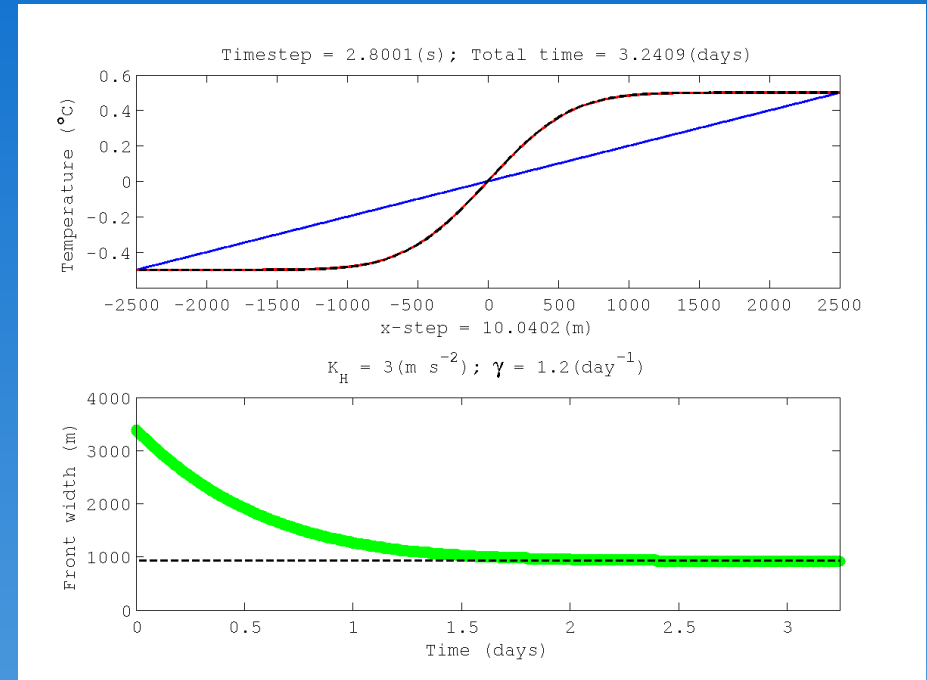
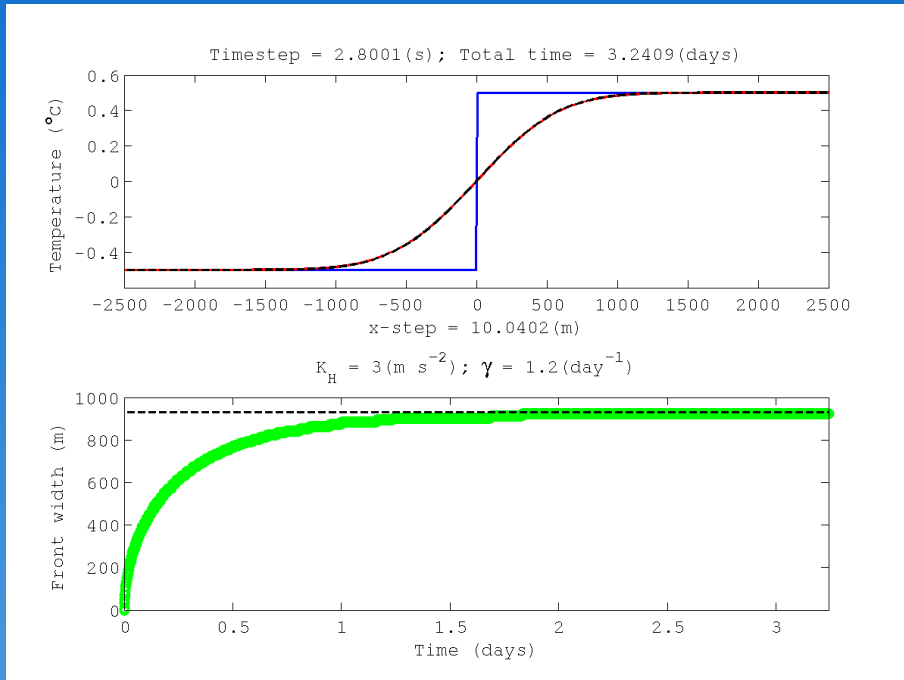


F. Nencioli, F. d'Ovidio, A. Doglioli, A. Petrenko  
**Surface coastal circulation patterns by in-situ detection of Lagrangian Coherent Structures.**  
*Geophysical Research Letters*, 38, L17604, doi:10.1029/2011GL048815

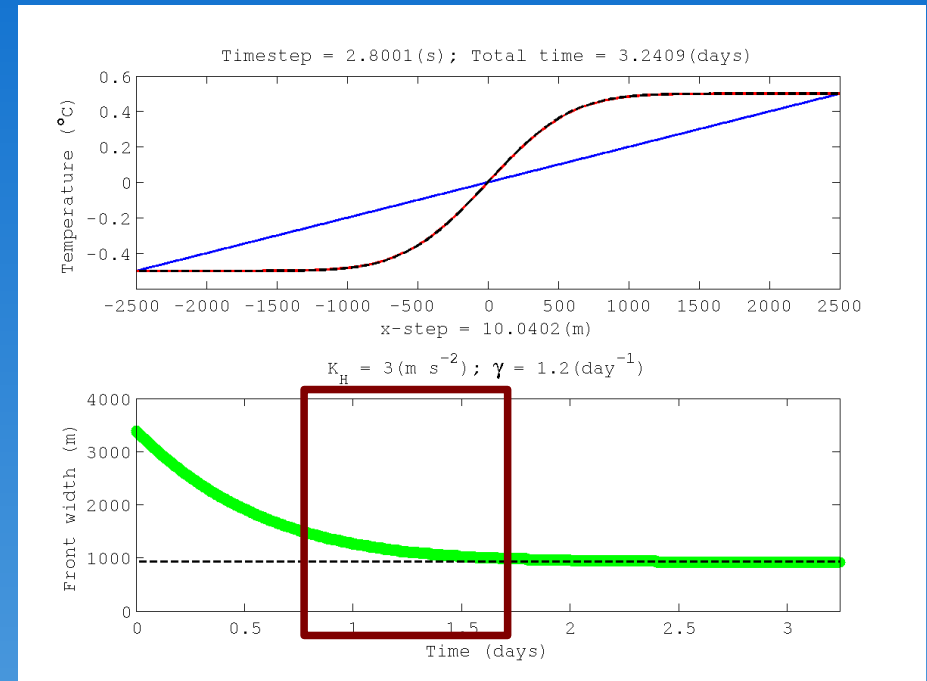
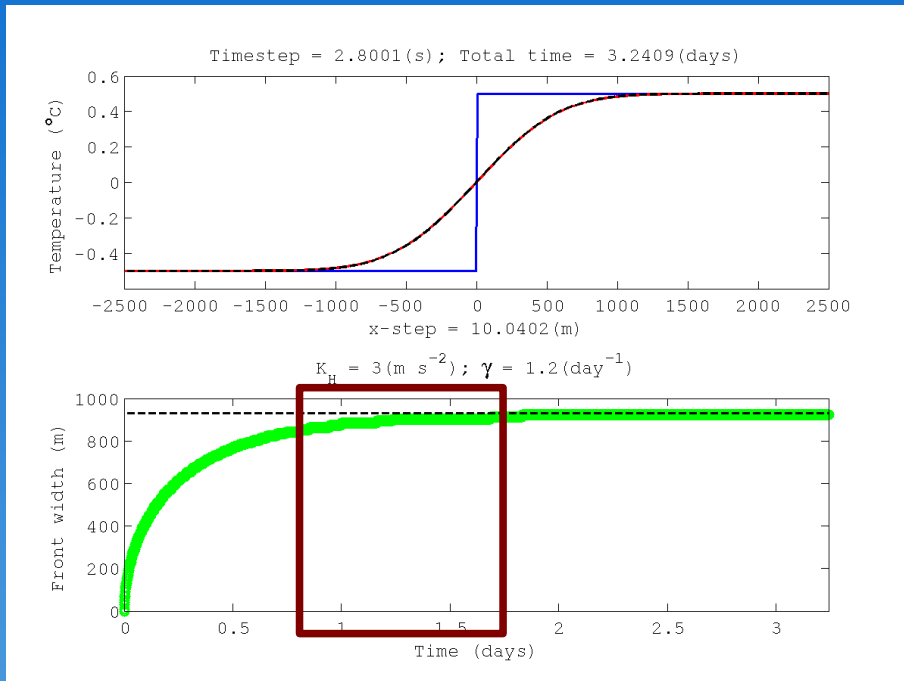
**LATEX website:** [www.com.univ-mrs.fr/LOPB/LATEX](http://www.com.univ-mrs.fr/LOPB/LATEX)

**EXTRA SLIDES**

## First order upwind scheme



## First order upwind scheme



- Fast adjustment to equilibrium (within 1 day)
- However  $K_H$  proportional to square of width
- Even small errors in width could affect estimate of  $K_H$